Development of Car/Trailer Handling and Braking Standards. Vol. IV: Technical Report for Phase II – Front Wheel Drive Tow Cars NTIS, November 1979

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# DEVELOPMENT OF CAR/TRAILER HANDLING AND BRAKING STANDARDS

Volume IV: Technical Report for Phase II—Front Wheel Drive Tow Cars

Richard H. Klein Henry T. Szostak

Systems Technology, Incorporated 13766 South Hawthorne Boulevard Hawthorne, California 90205

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# 15. Supplementary Notes

#### 16. Abstract

This report verifies the handling and braking performance requirements proposed in Vol. II for passenger cars towing trailers. This includes straight line braking, trailer swing stability, tow car steady turn stability, and combined brake-in-turn stability. Over 500 combinations vehicle tests with three trailers and two front wheel drive tow cars (in 34 different configurations), plus the results of previous trailer towing research have been integrated into proposed performance criteria, and a compliance format based on tow car and trailer characteristics. For straight line braking performance a combination-vehicle (CV) deceleration criteria of 0.4g is recommended. A tow car weight requirement based on trailer brake capability is presented to insure the CV will meet this deceleration requirement. For unbraked trailers the tow car gross weight rating should never be less than 1.5 times the trailer weight. For trailer swing stability the safety-related performance measure is damping ratio, or the equivalent cycles to one-half amplitude. A minimum damping ratio of 0.15 (or 3/4 cycles to 1/2 amplitude) is recommended. Test procedures and analysis curves are presented which can be used to determine damping ratio for each trailer. In this case a minimum hitch load criteria based on tow car weight is suggested to insure performance compliance. For tow car stability a tentative performance criteria of maintaining a positive tow car understeer gradient up to and including 0.3g cornering is recommended. This requirement sets a limit on the maximum allowable hitch load for a given weight tow car, and is a function of load leveling torque

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## ABSTRACT (Concluded)

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#### FOREWORD

This document comprises Vol. IV of a four volume technical report aimed at developing car/trailer handling and standards. A condensed executive summary of the entire program and key results is given in Vol. I. Volume II contains the main technical discussion and summary test results with three rear wheel drive tow cars. Volume III contains appendicies providing raw data and other supportive material for the Phase I tests. Results of Phase II testing, with two front wheel drive tow cars is presented in this volume. These tests represent a validation of the requirements proposed in Vol. II.

The research program was accomplished by Systems Technology, Inc., Hawthorne, California, for the Office of Passenger Vehicle Research of the National Highway Traffic Safety Administration, under Contract DOT-HS-7-01720. The contract technical manager was Dr. J. Kanianthra, and the STI project engineer was Mr. R. Klein. The STI Technical Director was Mr. I. L. Ashkenas.

Significant contributions made by STI staff members include Mr. H. T. Szostak for test direction and data analysis, Mr. L. Ingersoll for vehicle instrumentation and maintenance, Mr. S. Whitfield for test driving, and Ms. S. A. Riedel for development of the automated data reduction techniques.

Special acknowledgement is given for the fine cooperation and assistance extended to this program by the following organizations and individuals:

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#### TABLE OF CONTENTS

																				Page
I.	INT	RODUC	CTION	τ.	•	•		٠		•		•	•		•	•	•	•	•	1
II.	TES:	r Pro	GRAN	1.	•		•				•			•		•	•	•		3
	Α.	Tow	Veh	icles	and	Tr	ail	er	Sel	ect	ion	•	•		•	9	•	•	•	3
	В.	Tes	t Cor	ıfigu	rati	on	Sum	mar	У	•	•	•	٠	•	•	•	•	٠	•	5
III.	STRA	AIGH	r LII	VE BF	RAKIN	G	•	٠	•			•	•	• .	•	•	•	•	•	7
	A.	Unb:	rake	i Tre	ailer	S		•	•	•	•	•	•	•	•	•	•	•	•	11
	В.	Sur	ge Bi	rake	Trai	ler	•	•	•	•	•	٠		•	•	•	٠	•	٠	16
	C.	Ele	ctri	e Bra	akes	•	•	•	•	•	•	٠	•	•	•	٠	•	٠	٠	16
IV.	TRA:	ILER	DAM	PING	PERF	ORM	IANC:	Ē	•	•	•	•	•	•	•	•	•	٠	*	18
٧.	TOW	CAR	STE	ADY-S	STATE	TU	RN	STA	BIL	ITY	•		•		•		•	•	•	29
VI.	COM	BINE.	D BR	<b>AKI</b> INO	AND	CC	RNE	RIN	īG	•			•	•	• .	•		•	•	<b>3</b> 5
VII.	CON	CLUS	IONS	AND	RECO	MME	NDA	TIC	NS				٠	٠						39
	A.	Han	dlin	g and	i Bre	kir	ıg P	erí	orn	anc	e C	rit	eri	. <b>8</b> .		٠	•	e		39
	В.			•	nsuri						•	•	•		•	•	•		•	40
REFER	ENCE	s.	•	•		•	•		•		•	•	•	•	•	•	•	•	•	41
APPEN	DIX.	A.	TOW	VEHI	CLE A	ND	TRA	ILE	er s	PEC	IFI	CAI	TOI.		•	•	•	•	•	A-1
APPEN	DIX	B	RUN	LOG :	SUMMA	RY	•	٠	٠	•	•	•	•		•	•	•	•	•	B-1
APPEN	ŒŒ	c.	STRA	IGHT	LINE	BE	RAKE	T	CST	DAT	A	•	•	•	•	•		•	•	C-1
APPEN	ID IX	D.	TRAI	LER :	D <b>AMP</b> ]	□NG	RAI	OI.	DAT	EA.	•	•	•		•	•	•	•	٠	D-1
איי#סכר ∆	TTY.	Ŧ	ጥረጎኒኒ	CAR	STPATES	FT. T	ਸ ਪਾ	A CIT	IVE	דים	Δ		_		_					E-1

# LIST OF FIGURES

		Page
1.	Recommended Tow Car/Trailer Weight Limit to Meet O.4 g C-V Deceleration Requirement	. 8
2.	Comparison of Citation CV Straight Line Brake Performance with Proposed Criterion	. 12
3,	Comparison of Horizon CV Straight Line Brake Performance with Proposed Criterion	. 12
4:	Unbraked Trailer Stopping Performance Versus Trailer to Two Car Weight Ratio. Citation Tow Car	. 13
5.	Unbraked Trailer Stopping Performance Versus Trailer to Tow Car Weight Ratio; Horizon Tow Car	. 14
6.	Effects of Hitch Load on Unbraked Trailer Stopping Distance	• 15
7.	Trailer Damping of Combination-Vehicle at 55 mph as Function of Hitch Load	. 20
8.	Minimum Hitch Load Boundary Necessary for Trailer Damping of 0.15 at 55 mph	. 23
9.	Damping of Utility Trailer at Various Trailer Weights and Hitch Loads	. 26
10.	Speed Adjustment Curves Derived from Full Scale Tests	. 27
11.	Proposed Maximum Allowable Hitch Load Boundary to Provide Understeering Tow Car up to 0.3 g Cornering	. 30
12.	Variation in Tow Car Understeer Gradient with Hitch Load	. 33
13.	Comparison of Understeer Results with Proposed Maximum Hitch Load Boundary	. 34
14.	Recommended Integrated Trailer Handling Standard Examples	. 42
-1.	Plymouth Horizon Brake Gain Test Data Run Nos. 124-132	. A-4
-2.	Brake Force vs. Hydraulic Line Pressure for Surge Brake Trailer	. A-5

		Page
A-3.	Hydraulic Brake Pressure vs. Applied Horizontal Hitch Force for Surge Brake Trailer	A-6
A-4.	Brake Force vs. Applied Trailer Brake Voltage for 16' Travel Trailer	<b>A-</b> 7
A-5.	16' Travel Trailer Leaf Spring Suspension Geometry as Measured on Test Trailer	<b>A-</b> 8
D-1.	Run 72, Horizon with 1500 lb U-Haul 0% HL	D-10
D-2.	Run 68, Horizon with 1500 lb U-Haul 5% HL	D-11
D-3.	Run 63, Horizon with 1500 lb U-Haul 10% HL	D-12
D-4.	Run 46, Horizon with 1500 lb U-Haul 15% HL	D-13
E-1.	Understeer Gradient for Citation alone, Run 21	E-2
E-2.	Understeer Gradient for Citation Alone — After Trailer Tests, Run 243	E-3
E-3.	Understeer Gradient for Citation with 1500 lb U-Haul, 5 percent HL, Run 69	E-4
E-4.	Understeer Gradient for Citation with 1500 lb U-Haul, 10 percent HL, Run 68	E-5
E-5.	Understeer Gradient for 1500 lb U-Haul, 15 percent HL, Run 41a	E-6
E-6.	Understeer Gradient for Citation with 1500 lb U-Haul, 20 percent HL, Run 40	E-7
E-7.	Understeer Gradient for Citation with 1600 lb Camper, 10 percent HL, Run 107	E-8
E-8.	Understeer Gradient for Citation with 2400 lb Travel, 10 percent HL, Runs 183b, 184, and 185	E-9
E-9.	Understeer Gradient for Citation with Travel Trailer, Rear Wheels off Ground, Run 247	E-10
E-10.	Understeer Gradient for Horizon Alone, Run 20	E-11
E-11.	Understeer Gradient for Horizon Alone — After Utility and Camper Trailer Tests, Run 133	E-12
	Understeer Gradient for Horizon with 1500 lb	E-13

									Page
E-13.	Understeer Gradient for Horizon with 1500 U-Haul, 5 percent HL, Run 65				•	•		•	E-14
E-14.	Understeer Gradient for Horizon with 1500				•	Þ			E÷15
E-15.	Understeer Gradient for Horizon with 1500 U-Haul 15 percent HL, Run 53		•	•	•	•	•		E-16
E-16.	Understeer Gradient for Horizon with 1500 U-Haul 20 percent HL, Run 35			٠	•	•		•	E-17
E-17.	Understeer Gradient for Horizon with 1600 Camper, 10 percent HL, Run 115	1b	•	e	•	•	٠	•	E-18
E-18.	Understeer Gradient for Horizon with 2400 Travel 10 percent HL, Run 201		•	•	•	÷	•	•	E-19

#### LIST OF TABLES

						rage
1.	Test Two Cars (Front Wheel Drive)	•	•	•	•	4
2.	Test Trailers	•	•	•	•	4
3.	Full Scale Test Summary	٠	ø	•	•	6
4.	Combination Vehicle Straight Stopping Distance Results for Chevrolet Citation	•	•	•		9
5.	Combination Vehicle Straight Line Stopping Distance for Plymouth Horizon	•	٠	•	•	10
6.	Trailer Damping Ratio Derived from Pulse Steer Tests	•	•	•		19
7.	Estimated Maximum Safe Speed and Unstable Speed for Each C-V Configuration	•	•	•		<b>2</b> 8
8.	Two Car Understeer — Constant Radius Circle Test Results	•	•	•	•	3 <b>1</b>
9.	Brake in Turn Results for Citation	•	•	•	•	36
10.	Brake in Turn Results for Horizon		•	•	•	37
A-1.	Test Vehicle Specifications	•	•	•	•	A-5
A-2.	Test Trailer Specifications	•	•		•	A-3
B-1.	Citation Test Runs	•		•	•	B-2
B-2.	Plymouth Horizon Test Runs	•	•	•	•	B-3
C-1.	Straight Line Brake Data for Chevrolet Citation	•	•	•	•	C-2
C-2.	Straight Line Brake Data for Plymouth Horizon	•	•	•	•	c-6
D-1.	Combination-Vehicle Damping Ratio Results with Chevrolet Citation	•	٠	•	٠	D-5
D-2	Combination Vehicle Damping Ration Results with					n-6

	·	,

#### SECTION I

#### INTRODUCTION

This report presents results of a second phase of a program to develop braking and handling performance criteria, and compliance formats for passenger cars towing trailers. In the first phase of the study (described in Vols. II and III) a full range of trailers were tested with three different tow cars representing the intermediate (Chevrolet Monte Carlo), compact (Plymouth Volare), and sub-compact (Ford Mustang) vehicle classes; the selection being based on weight difference and manufacturer.

During this, and the previous Ref. 1 study, it was determined that weight distribution plays a significant role in trailer towing handling and braking. Consequently, increasing hitch load, and/or load leveling, significantly alters the tow vehicle stability and stopping distance. For example, the use of load leveling to obtain a "level" car/trailer attitude does not provide equal weight transfer when the front springs have a higher rate than the rear springs; stopping distance is unfavorably affected with uneven front/rear brake proportioning; and higher than normal throttle application (due to trailer load) affects steering characteristics in steady turns. Because of these factors it appeared desirable to expand the research tests to include trailer towing test procedures for front-wheel drive vehicles. These vehicles typically have a very uneven (63/37) front/rear weight distribution, and are becoming a large portion of the in-use population.

In regard to the trailers capable of being towed by this subcompact vehicle class, structural and engine power capabilities limit the overall trailer weight and hitch load. Consequently, tests were made with three trailers at various weights to uncover the limitations.

Following the format of Vol. II (for the 3 rear wheel drive vehicles) this report is organized according to the 4 key test procedures. These comprise straight line brake (for stopping performance), pulse steer (for trailer swing performance), constant radius circle (for tow car stability), and brake-in-turns (for combined longitudinal and lateral stability and performance). Results of each procedure, with comparison to the rear wheel

drive test cars, are presented in individual sections. For summary, the test program overview is presented first, and the overall conclusions and recommendations are presented last.

#### SECTION II

#### TEST PROGRAM

This second phase of the test program sponsored under the Ref. 2 contract involved testing two additional passenger cars with three trailers. This section presents data for these vehicles and the test matrix of combination-vehicle configurations.

#### A. TOW VEHICLES AND TRAILER SELECTION

Two subcompact front-wheel drive vehicles were selected. These were the new GM X body, a Chevrolet Citation, and a Plymouth Horizon. As noted in Table 1, the Citation weighs about 500 lbs more than the Horizon and has a higher front weight distribution.

Based on structural and suspension limitations it is not possible to tow more than Class II trailers (3500 lbs) with these subcompacts. In fact, the manufacturers do not recommend towing any trailer over 1000 lbs unless the tow car has some trailering options. Even with this, the user is cautioned never to tow any trailer over 2000 lbs! For example, Chevrolet provides the following caution in their owners manual:

CAUTION: Do not try to tow any trailer over 2,000 pounds (900 kilograms) gross trailer weight (1,000 pounds (450 kilograms) for California emission equipped cars with air conditioning) no matter what trailer towing equipment is installed. This could seriously affect your car's performance, durability or handling, which could result in personal injury.

However, in order to determine the maximum allowable trailer weights and hitch loads, three single axle trailers were selected. As noted in Table 2, these represented a non-braked utility trailer (GVWR 2600 lb), a camper trailer with surge brakes, (GVWR 2100 lb), and a light weight, electric braked, travel trailer (GVWR 3000 lb). Load leveling could not be used with the subcompact vehicles since they can not accompact a third class hitch, however, air shocks were available for the Citation and provided the capability to maintain a constant rear suspension ride height with up to 350 lbs hitch load. The Horizon did not have an air shock replacement.

TABLE 1. TEST TOW CARS (FRONT WHEEL DRIVE)

VEHICLE TYPE (GVWR)	SIZE	CURB WEIGHT/ TEST WEIGHT <sup>a</sup> (1bs)	WHEELBASE (in.)	TIRESÞ	WEIGHT DISTRIBUTION F/R <sup>C</sup>
1979 Chevrolet Citation (3571)	Sub-Compact	2722/3200	105.	P185/80R-13 TPC 1029	62/38
1978 Plymouth Horizon (3165)	Sub-Compact	2250/2675	.66	P155/80R-13	58/42

aIncludes driver (180 lbs), instrumentation (275 lbs), hitch, and one-half fuel. binflation pressures: 35/35 (cold inflation pressure for max. rated load). cAt test weight

TABLE 2. TEST TRAILERS

TVPE	MANUFACTURER/ MODEL	OVERALL	TEST WEIGHT GVWR	AXLES	BRAKES	TIRES (PRESSURE)
Utility	U-Haul/AV	11 ft 6 in.	2600 1500/2600 1000	-	None	6:70×15 LT LRC (45 psi)
Camper	Starcraft Starmaster 6	15 ft 3 in. 1600/2090	1600/2090		Surge 7×1.75	5:30×12 LRC (80 psi)
Small Travel	CAL-CAMP	16 ft 4 in.	2400/3000 3000/3000	***	Electric 10×2 (Kelsey-Hayes)	7:00×14 LRC (36 psi)

#### B. TEST CONFIGURATION SUMMARY

A total of 34 different combination-vehicle configurations were tested. These were obtained by varying trailer weight, hitch load, and trailer brake capability on the three test trailers pulled by two tow cars. The exact configurations are listed in Table 3 along with the test procedures applied. A thorough discussion of each test procedure is given in Vol. II.

TABLE 3. FULL SCALE TEST SUMMARY

	TES	ST CONFI	GUR/	TION	Ţ				TI	ST	PRO	CEI	URE	S			
TRAILER	WEIGHT	HITCH LOAD	A: SHO		BRAKES	C C	RT P	P C	S P	SI C	B P	B] C	T P	B' C	ra P	OTH C	ŒR P
Utility	1000	0		N	N				×								
		10	Y	N	N			×	×								
-	1500	0	N	N	N		×	×	×	×	×						
		5	Y	N	И	×	×	×	×	×							
•	enverendra de la companya de la comp	10	Y	N	N	×	X	×	×	×	×						
,		15	Y	N	N	×	X	×	X	×	×	×	×			age against the same	
		20	Y	N	N	×	×										
***************************************	2600	5		N	N				×								
		10	Y	N	N			×	×	×	×						
Camper	1600	0	N	N	_			×	×								
_	70 m	5	Y	N				×	×								
		10	Y	N	YY	×	×	×	×	×	×			×			X
		10	Y		N					×		×					•
		15	Y	N	Y Y			×	×				×				
Travel	2400	5	Y	N				×	×								
		10	Y	N	0% N					×			×				×
		10	Y	N	50%					×							
		10	Y	N	100% Y	×	×			×	×	×	×	×			×
		15	Y	N	-			×	×								
	3000	10		N											×		

Hitch Load = Percent trailer weight
Air Shocks = Yes if used to level CV,
No if not used

CRT = Constant radius turn (400 ft diameter)

PS = Pulse steer at 55 mph

SLB = Straight line brake from 40 mph

BIT = Brake in turn, 40 mph, 0.3 g turn

BTA = Trailer-alone brake

Other = 0.6 g tow car brake capability

C = Chevrolet; P = Plymouth

#### SECTION III

#### STRAIGHT LINE BRAKING

Based on the previous tests of eight trailers and three tow cars it was recommended (in the Vol. II report) that the straight line stopping performance for combination-vehicles be 134 ft from 40 mph. This corresponds to an average deceleration of 0.4g.

To insure compliance, it was further recommended that the tow car to trailer weight ratio,  $W_c/W_t$ , be proportion to the "trailer-alone" deceleration capability,  $a_{\rm xta}$ . Specifically,  $W_c/W_t$  be greater than 2.1 minus 3.5  $a_{\rm xta}$ , i.e.,

$$\frac{W_c}{W_t} \geq 2.1 - 3.5 a_{x_{ta}}$$

Basically, this requires the tow car to be at least 2.1 times the trailer weight if there are <u>no</u> trailer brakes. With trailer brakes providing a 0.43 g capability (a typical design) the trailer could actually be heavier than the tow car.

This braking expression was derived from a complete static braking model with 10 percent hitch load, non-optimum brake proportioning (60F/40R) and no load leveling (see Appendix D of Vol. III). It is more readily interpreted when illustrated graphically as in Fig. 1. In this plot, tow car to trailer weight ratios above the boundary would theoretically pass the stopping distance requirement, and weight ratios below (or inside) the shaded boundary would fail the requirement.

One of the key objectives of this second testing phase was to verify the proposed boundary, especially for unbraked trailers where the proposed standard could restrict some current designs (i.e., since some states allow 3000 lb unbraked trailers).

A second objective was to determine if the proposed requirements, based solely on rear wheel drive passenger cars, were also applicable to front wheel drive designs.

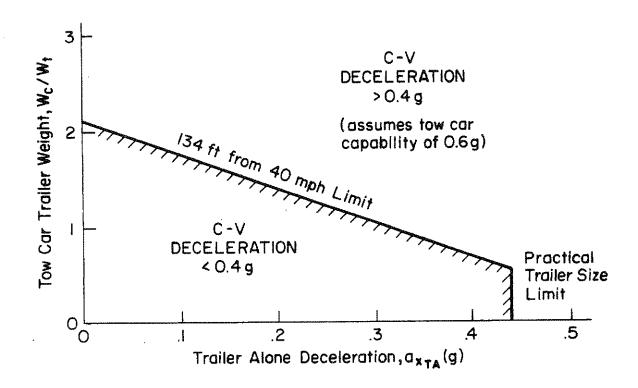


Figure 1. Recommended Tow Car/Trailer Weight Limit to Meet 0.4 g C-V Deceleration Requirement

As described in Vol. II, the straight line brake test procedure involves maximum performance stops from 40 mph. At least six replications are made, in which incipient tow car lockup is allowed, i.e., preferably 3 runs below lockup and 3 runs with partial lockup.

The average test results for each tow car and C-V are presented in Table 4 and 5. Individual test run data are presented in Appendix B of this volume. First, in regard to tow car alone performance, both vehicles met (or exceeded) the requirements of FMVSS-105-75. The Citation was close to the stopping distance requirement (89.3 ft average vs. 91 ft required) and the Horizon was well below (at 79.3 ft or 0.68 g average). In addition, the Citation exhibited a front wheel lockup limitation whereas the Horizon exhibited rear wheel lock-up. For optimum car alone performance, the front lock-up is

COMBINATION VEHICLE STRAIGHT LINE STOPPING DISTANCE RESULTS FOR CHEVROLET CITATION  $^{\mathrm{b}}$  - NO LOAD LEVELING-AIR SHOCKS ONLY TABLE 4.

CONDITION HITCH LOAD	1	UTILITY (NO BRAKES)		CAMPER (1600 lb) NO BRAKES SURGE	600 lb) SURGE	TRAVEL (2400 NO BRAKES 58% BR		100% BR	CAR /	CAR ALONE ORE AFTER
0		112±2.7					and the property of the proper		88.0±4.1 90.6±4.3	90.6±4.3
<b>ا</b> ر		117±2.5								
01	107 ± 5.7	116±4.6	155 ± 7.8	126±6.3	113±1.6	155 ± 7.8 126 ± 6.3 113 ± 1.6 141 ± 6.0 114 ± 4.9 98 ± 1.7	114±4.9	98 ± 1.7		
15		120±4.5								

astopping distance, in feet, from 40 mph, mean  $\pm$  std dev, Number of runs in corner; tow car lockup permitted.

b3200 lb test weight

COMBINATION VEHICLE STRAIGHT LINE STOPPING DISTANCE  $^{\rm a}$  FOR PLYMOUTH HORIZON  $^{\rm b}$  . NO LOAD LEVELING. NO AIR SHOCKS. TABLE 5.

	CAR	AIONE	. R 79.3 ± 2.45		
IB	NO BRAKES	.6 g TOW CAR		137. ± 1.83	
TRAVEL, 2400 LB	100% BRAKES	.6 g TOW CAR		86.9 ± 3.19	
TRAV	100% I	MAXIMUM TOW CAR		F 79.4 ± 1.89	`
CAMPER, 1600 LB	NO BRAKES	.6 g Tow car		118. ± 1.47	;
CAMPER,	NO BI	MAXIMUM TOW CAR		F or R 97.8 ± 2.82	
	1500 L.B 2600 L.B	CAR		F 128. ±	
ULILITY	1500 LB	(MAXIMUM TOW CAR PRAKING)	R 115. ± 1.93	F 96.3 ± 2.75	F 99.3 ± 1.18
	1000	(MAX		В 88.2± 2.09	
CONDITION	HITCH	IOAD	%o	10%	15%

<sup>a</sup>Stopping distance, in feet, from 40 mph, mean t standard deviation of six tests at maximum deceleration, tow car lockup noted, i.e., R = Rear Wheel Lockup Limited and F = Front Wheel Lockup Limited.

<sup>b</sup>2675 lb test weight

desired. However, for trailer towing, the rear lock limitation is beneficial since the increased rear tire load provided by the trailer hitch load can be turned into braking force. On the other hand, a vehicle nominally exhibiting front wheel lock-up will lose overall braking capability when trailer towing since increasing hitch load continually unloads the front axle, thus making lock-up even more premature.

In regard to CV braking performance, most tests were performed with a 10 percent hitch load, however one trailer was tested at hitch loads from 0 to 15 percent (in 5 percent increments) to evaluate the differences due to tow car lock-up. Various trailer weights and braking capability were also tested in order to provide a comparison with Fig. 1. Since the performance boundary of Fig. 1 was based on a 0.6 g tow car (per 105-75) it was desirable to test both tow cars at this level. The Citation was already close enough, however the Horizon required reduced brake force levels in order to simulate the 0.6 g tow car. Stopping distances increased accordingly. Figures 2 and 3 compare the stopping distance results with the predicted performance boundary. Using these figures we will discuss the performance of each type of trailer brake system.

#### A. UNBRAKED TRAILERS

As noted previously, the recommended tow car to trailer weight ratio of 2.1 shown in Figs. 2 and 3 for unbraked trailers may be criticized since it would impact on some current trailers, and the boundary has not been adequately validated. Indeed, test results indicate that the performance of front wheel drive CV's exceed the predictions, and in fact, are performing with near-optimum brake force proportioning. For example, it was shown in Vol. II (Fig. 3) that a 1500 lb unbraked trailer could, ideally be stopped in 134 ft (at 0.4 g) by a 0.6 g tow car if the tow car weight was greater than 2150 lbs, i.e., a tow car to trailer weight ratio of 1.5. This is very close to the performance achieved by the Citation plus unbraked trailer combinations in Fig. 2.

To more accurately determine the weight ratio necessary to achieve a 134 ft stopping distance from 40 mph, we can plot stopping distance versus trailer to tow car weight ratio. This form of presentation provides a nearly

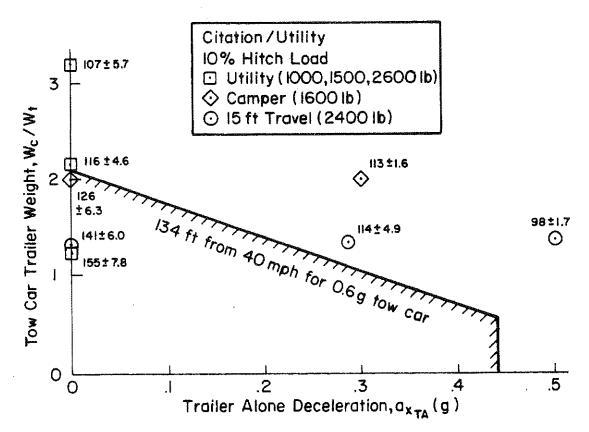


Figure 2. Comparison of Citation CV Straight Line Brake Performance with Proposed Criterion

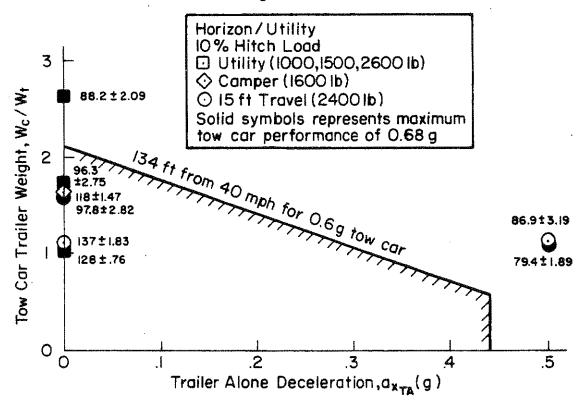


Figure 3. Comparison of Horizon CV Straight Line Brake Performance with Proposed Criterion

linear relationship such as shown by the dashed line in Fig. 4. The actual data very closely matches the optimum brake force curve and shows that the trailer should not weigh more than 67 percent of the tow car.

With higher car-alone performance, plus rear lock-up tendency, the Horizon with unbraked trailers provided even shorter stopping distances. This is shown in Fig. 5. Since all analysis and criterion must assume a tow car just meeting the FMVSS-105-75 requirement of 91 ft from 40 mph the open symbols shown in this figure represent that performance capability. These data points are also below (i.e., better than) the optimum brake force line because the rear lock-up tendency increases overall brake force as hitch load is increased. Only when hitch load exceeds 150 lbs does the front axle unload sufficiently to cause front wheel lock-up.

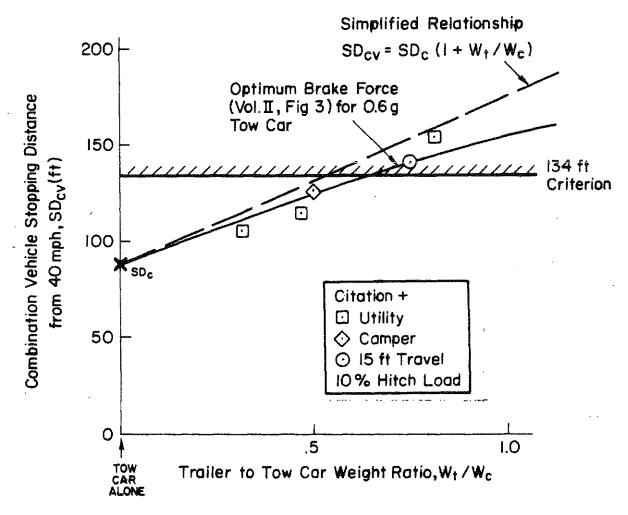


Figure 4. Unbraked Trailer Stopping Performance Versus Trailer to Tow Car Weight Ratio. Citation Tow Car.

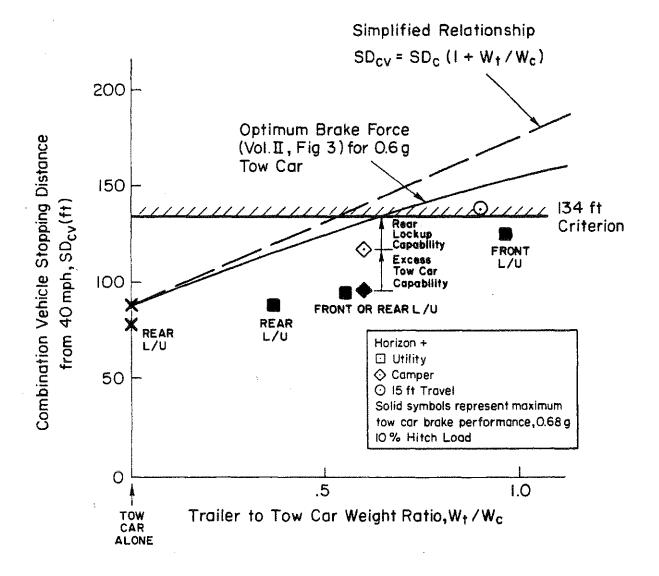


Figure 5. Unbraked Trailer Stopping Performance Versus Trailer to Tow Car Weight Ratio; Horizon Tow Car

The effects of hitch load (for both tow cars) are shown more directly in Fig. 6. The Citation follows the nominal (or anticipated) trend of increased stopping distance with increased hitch load. The Horizon exhibits the reverse trend at low hitch loads (due to increasing brake force capability at the rear) up to about 150 lbs at which point front lock-up occurs and further increases in hitch loads increase stopping distance.

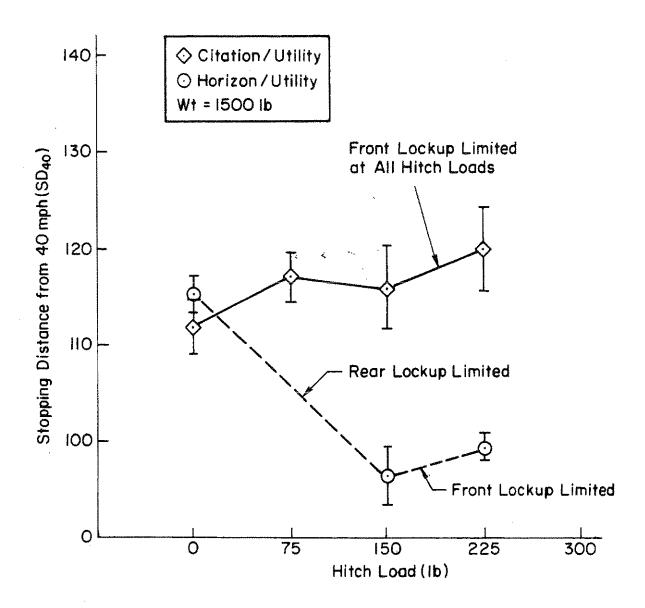


Figure 6. Effects of Hitch Load on Unbraked Trailer Stopping Distance

#### B. SURGE BRAKE TRAILER

Surge brakes on the camper trailer improved stopping distance from 126 ft to 113 ft. This is not as much as possible since the trailer alone brake capability was only 0.3 g. This value is based on the surge brake gain, G, the desired combination vehicle deceleration,  $a_{\rm X_{CV}}$ , and the hitch load. Specifically, from Vol. II, pg. 32.

$$a_{xta} = \frac{a_{xcv}[G/(1+G)]}{1 - \frac{\%HL}{100}}$$

For this trailer the surge brake gain was determined to be 2.1 (see Appendix A) the hitch load was 10 percent, and desired deceleration criterion was 0.4 g. Inserting these figures yields a trailer alone deceleration capability of 0.296 g.

It was also shown in Vol. II that with surge brakes a surge trailer should stop in a distance equal to an unbraked trailer of weight:

$$W_{No Brakes} = \frac{W_{With Surge}}{G + 1}$$

or 516 lbs when G = 2.1. Referring back to Fig. 4, the surge brakes should, ideally, produce CV stopping distance of 100 ft, or 26 ft better than the no brake case. Since the actual improvement was only half this value the surge mechanism was not functioning as well as possible; probably due to onset delays (usually 0.3 sec) and sliding friction (see hystersis plot in Appendix A).

#### C. ELECTRIC BRAKES

Two configurations of electric brakes were tested; maximum and 58 percent. This latter represents a 0.29 g trailer alone capability and was set using the trailer alone calibration curve presented in Appendix A. The full trailer brakes provided 0.5 g capability at full GVWR (3000 lbs). As anticipated this maximum trailer alone level provided a CV capability well above the proposed 0.4 g requirement (refer to Figs. 2 and 3). At the reduced brake force level the CV was still able to exceed 0.4 g.

These results are consistent with the recommendations of Vol. II that no more than 1500 lbs should be supported by each 10 in. brake. At 1200 lbs per brake, the test trailer was well below the maximum recommended.

A summary of the straight line braking results, and implications for modifying the tow car to trailer weight recommendations are presented in Section VII.

The primary problem that will occur in meeting the straight line brake and brake in turn requirements is specifying the tow car weight necessary for unbraked trailers. This occurs because some states allow unbraked trailers up to 3000 lb. For example, it was recommended in Phase I, for rear wheel drive tow cars, that the tow car be a minimum of 2.1 times the trailer weight. In this phase we have determined that for front wheel drive cars this multiplier can be reduced to 1.5. This value definitely represents a lower bound, since it represents optimum brake force at both front and rear. If we hope to meet (or exceed) a 0.4 g CV deceleration requirement with all tow vehicles, the 2.1 value represents a more conservative recommendation. However, even assuming the more optimistic value of 1.5, the 3000 lb unbraked trailers would have to be towed by at least a compact sized vehicle (GVWR ≥ 4500 lb). If such a restriction is not possible, the overall stopping distance requirement will have to be relaxed. This would, however, be inconsistent with the stopping capability of braked trailer combinations.

For braked trailers the recommended tow car to weight ratio selected above can be reduced by a factor of 3.5 times the "trailer-alone" braking capability (in g units), i.e.,

$$\frac{W_c}{W_t} \ge 1.5 - 3.5 a_{xta}$$

Current contemporary trailer manufacturers are providing 0.43 g capability, and test results from both phases showed 5 out of 7 trailers (with brakes) exceeding this value. Only when the trailer weight exceeded 1500 lb per each 2"  $\times$  20" brake did a trailer not meet 0.43 g. Assuming this trailer design criterion there would be no restriction on minimum tow car weight.

#### SECTION IV

#### TRAILER DAMPING PERFORMANCE

It was previously shown by test data in Vol. II that several key factors influence the trailer swing damping. In terms of providing an <u>improvement</u> in damping these were as follows:

- Increase tow car to trailer weight ratio (i.e., larger car or smaller trailer).
- Increase hitch load.
- Decrease moment of inertia about c.g. (i.e., reduce barbell effect).
- Reduce speed.

In addition it was shown, analytically, that increasing trailer effective tongue length,  $\ell_2$ , and increasing trailer tire cornering stiffness, Yaz, were also beneficial. Test data provided in this second test phase show that front wheel drive vehicles support the previous conclusions.

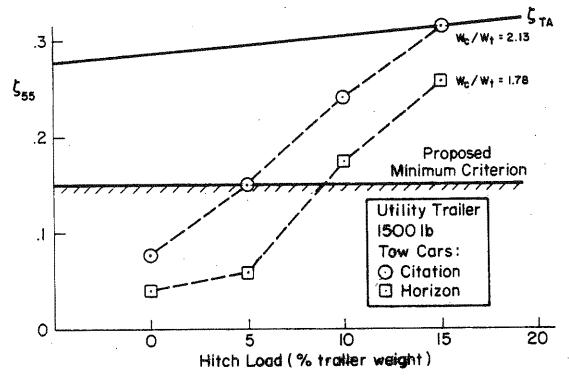
Twenty-eight combination-vehicle configurations were tested with the two front wheel drive tow cars and three trailers. Hitch loads were the primary variable, although trailer weight was varied with the utility trailer, and speed was varied for most configurations. Load leveling (via a weight distributing hitch) or sway dampers were not used. The average trailer damping ratio for each of these configurations is presented in Table 6. These data were derived from four individual test runs (see Appendix D) using a time series least squares fit to a pure second order system response.

The trends in trailer damping (at 55 mph) as a function of hitch load are graphically presented in Figs. 7a, b, and c for the three trailers. As expected, increased hitch load is the primary factor in improving trailer damping. In addition, it can be seen that for a given hitch load, the heavier tow car provides higher trailer damping.

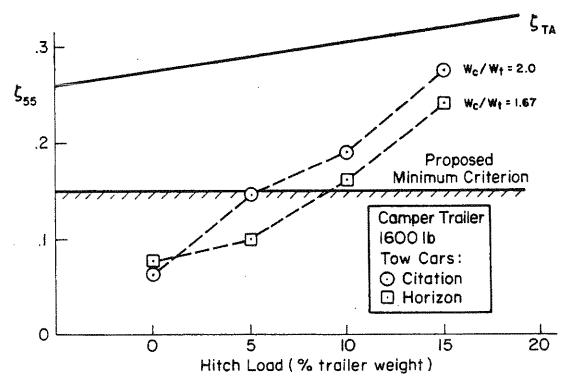
Also shown on Figs. 7a, b, and c are lines representing the maximum and minimum damping ratios. The former represents the analytical

TABLE 6. TRAILER DAMPING RATIO DERIVED FROM PULSE STEER TESTS

		TOW CAR/					HII	HITCH LOAD/SPEED	D/SP旺	e				
TRAILER	TRAILER	TRATILER		0			5			10			15	
		RATIO	35	45	55	35	45	55	35	45	55	35	45	55
Utility	1000	3.20							.370	.343	.327			
		2,68			-095		:	1 to	.256	.181	.165			
	1500	2.13	北1.	.116	920.	.361	.255	.148	.520	.274	Эфо	Lot:	#2 <b>†</b> .	.317
-		1.78	.166	.088	.039	.183	.104	.055	.320	.224	.173	844.	.308	-254
	2600	1.23							.344	.244	.183			
		1.03						.052	.225	.153	.101			
Camper	1600	2.0	.231	114	.062	.236	.183	.143	.321	.248	<u>.</u> 8	.511	.335	±775.
		1.67	234	.142	.076	.18	.157	.100	.322	.228	.161	.416	88	.242
16 Ft	2400	1.33				.196	.165	960.	.276	.195	.138	.318	.234	.217
Travel		1.12				.231	.145	190°	.280	.212	.128	.331	.243	194

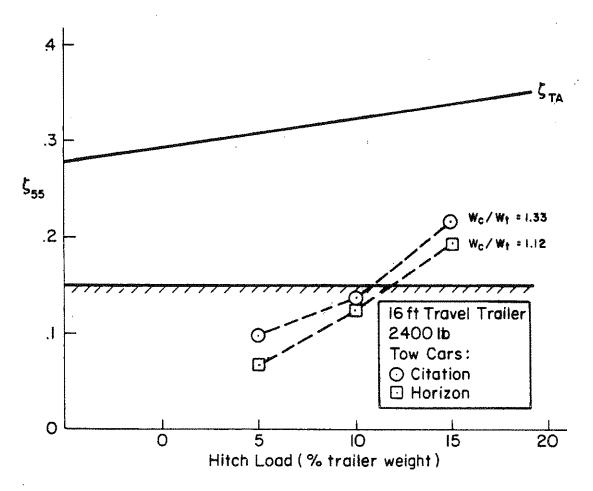


a) Utility Trailer



## b) Camper Trailer

Figure 7. Trailer Damping of Combination-Vehicle at 55 mph as Function of Hitch Load



c) Travel Trailer

Figure 7. (Concluded)

"trailer-alone" damping ratio. This corresponds to the maximum damping that each trailer could achieve, if, for example, it were pulled by a tow car of infinite mass, or if there was no lateral movement of the hitch point. In effect, it is a locus of hitch loads for a given trailer that locates the center of percussion (for forces applied at the trailer tires) at the hitch point. The latter line, drawn across at  $\zeta = 0.15$ , represents the proposed damping criterion. Where this line intersects a line connecting the data points represents the minimum allowable hitch load for that particular tow car to trailer weight ratio. Other tow car to trailer weight ratios can be derived by extrapolating the damping ratio points at other hitch loads. This has been accomplished and presented in Fig. 8 for each trailer, respectively. A comparison to analytical predictions can now be made.

Since two of the three test trailers used in this phase were also tested in Phase I with rear wheel drive tow cars, the Vol. II results have been overplotted on Figs. 8a and 8b. For example, in Fig. 8a, this comparison shows the FWD tow cars to be <u>less</u> prone to trailer swing than their RWD counterparts. In other words, the FWD tow car would allow a lighter hitch load than that necessary on an equivalent weight RWD tow car.

The analytically derived boundary lines are also shown on Fig. 8a and 8b. These lines were computed from the following equation previously presented in Vol. II:

$$\zeta_{\rm cv} = \frac{\sqrt{\ell_2 ^3 \gamma_{\rm c3}}}{U_{\rm o} \sqrt{2 I_{\rm th}}} - \left\{ \frac{I_{\rm to} - \frac{W_{\rm t} \ell_2^2}{g} \left[ \frac{HL}{100} - \left( \frac{HL}{100} \right)^2 \right]}{I_{\rm th}} \right\} C_1 \frac{W_{\rm t}}{W_{\rm c}}$$
Trailer Alone
Damping Ratio,
$$\zeta_{\rm TA}$$
Hookup Factor
Sensitivity

For the previous work an "average" tow car sensitivity constant of 3.7 was used. This value resulted in the predicted damping either matching or paralleling the full scale data. For the front wheel drive tow cars it appears that a lower value of C<sub>1</sub> (less tow car sensitivity) is more

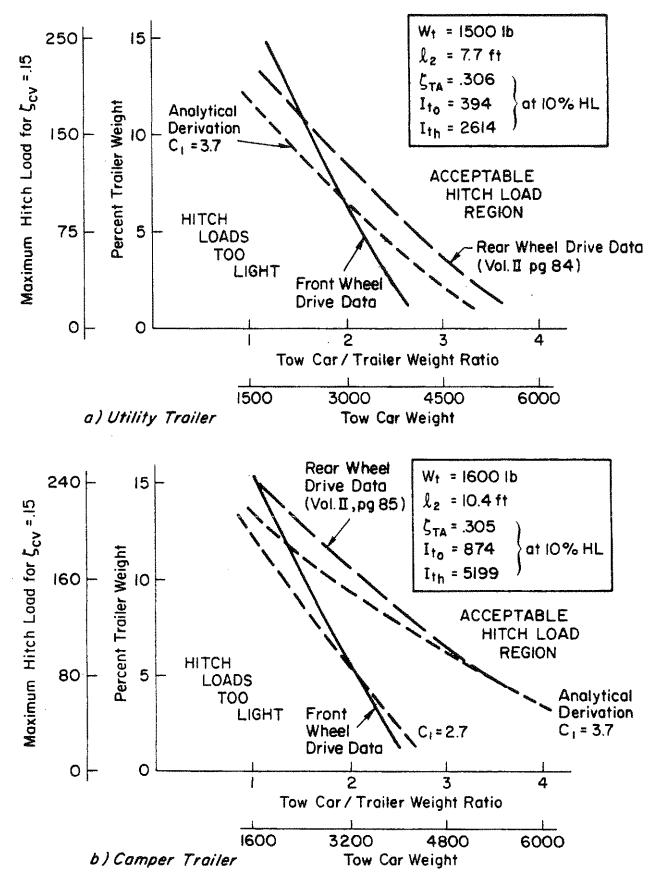
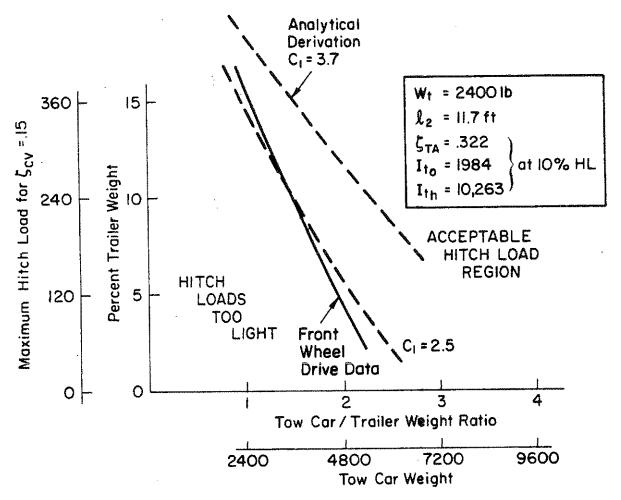


Figure 8. Minimum Hitch Load Boundary Necessary for Trailer Damping of 0.15 at 55 mph



c) 16 ft Travel Trailer

Figure 8. (Concluded)

appropriate. Analytically derived curves using these lower values of  $C_1$  are shown in Figs. 8b and 8c to illustrate the comparison with full scale data.

In the previous figures the trailer weight has been constant and the beneficial effects of increased tow car weight illustrated. The same trends hold true if, for a given tow car, the trailer weight is decreased. Verification of this trend is shown in Fig. 9 for the variable weight utility trailer. These results are as anticipated since a lighter trailer reduces the hookup factor and tow car sensitivity terms in the equation for combination vehicle damping ratio.

The effects of speed on trailer damping is the last discussion item. Speed adjustment curves such as derived in Vol. II, Appendix E are valuable for use in adjusting data points taken at off-nominal speeds, in predicting the maximum safe speed (for  $\zeta_{\rm CV}$  = .15), or the speed for trailer instability, i.e.,  $\zeta_{\rm CV}$  = 0. Since the previous curves were based on computer simulation and verified by only a few full scale tests it was desired, in this test phase, to check and refine the curves.

The data from Table 6 for 35, 45, and 55 mph (for each trailer at 10 percent hitch load) have been plotted in Fig. 10 for the two tow cars. Also shown on Fig. 10 are the speed adjustment curves used in Vol. II. The new curves are slightly shallower (less speed sensitivity) but do follow the shape of the previous curves. Using these new curves (or the ones sketched parallel) it is possible to estimate the speed at which a given trailer will cross the (proposed) minimum stability boundary and/or the unstable boundary. For example, Table 7 predicts these speeds for each CV configurations. Speed limitations such as suggested by Table 7 are another approach to a trailer safety standard, however, from an enforcement standpoint it would be more desirable to limit the hitch load so that the minimum safe speed is always equal to or greater than 55 mph.

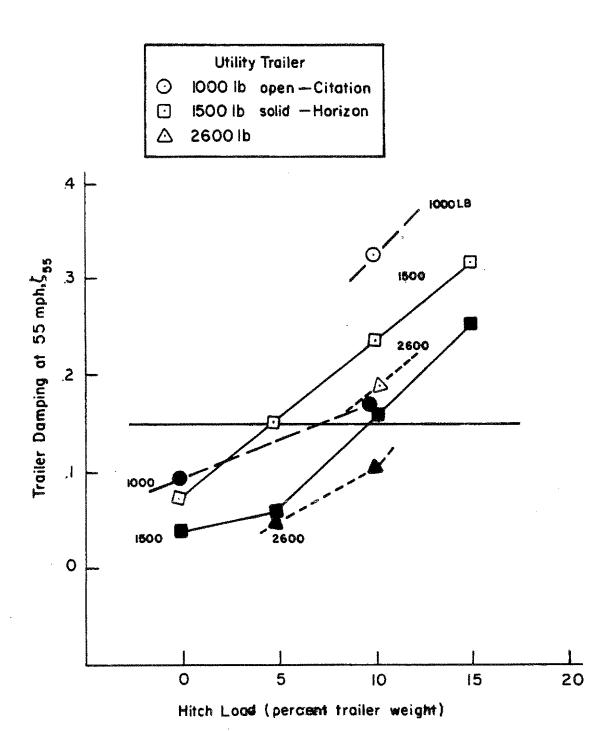


Figure 9. Damping of Utility Trailer at Various Trailer Weights and Hitch Loads

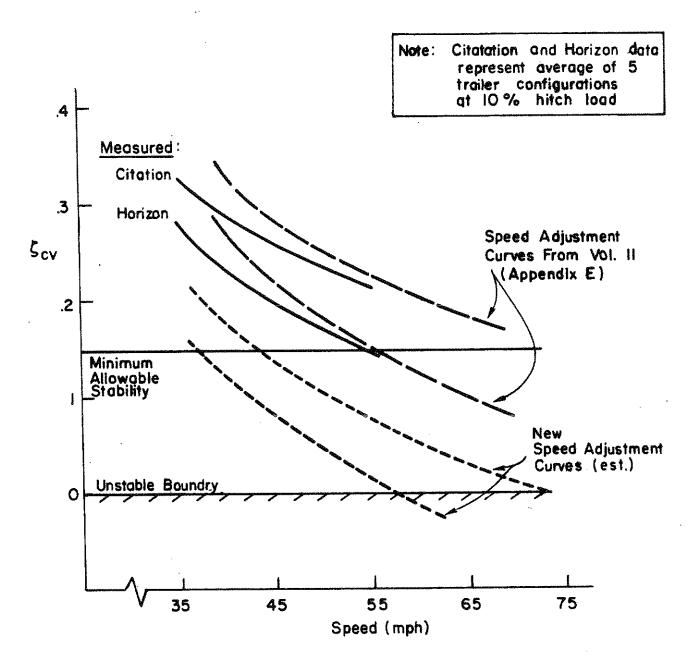


Figure 10. Speed Adjustment Curves Derived from Full Scale Tests

TABLE 7. ESTIMATED MAXIMUM SAFE SPEED AND UNSTABLE SPEED FOR EACH C-V CONFIGURATION

TOW CAR	TRAILER	HITCH LOAD	SPEED FOR $\zeta = .15$	unstable speed (mph)
Citation	Utility 1000	10	> 80	> 80
	1500	10	70	> 80
		5	54	> 80
		0	43	73
	2600	10	57	> 80
	Camper 1600	10	68	> 80
		5	54	> 80
		0	42	69
	Travel 2400	15	73	> 80
	!   	10	53	> 80
		5	47	79
Horizon	Utility 1000	10	58	> 80
		0	46	78
	1500	10	62	> 80
		5	41.	67
		0	39	63
	2600	10	47	79
		5	40	66
	Camper 1600	10	57	> 80
·		5	47	79
		0	43	73
	Travel 2400	15	68	> 80
	Services and the services are the services and the services and the services are the servic	10	51	> 80
		5	42	70

Note: Assumes low g cornering; speeds will be significantly lower if lateral acceleration exceeds 0.3 g or if trailer swing exceeds 10 deg.

### SECTION V

### TOW CAR STEADY-STATE TURN STABILITY

In Vol. II it was shown, both analytically and with test results, that adding hitch load reduced the tow car understeer. This reduction is amplified at higher lateral acceleration levels, and when load leveling is added. The performance measures used for evaluating these effects were understeer gradient at low lateral acceleration,  $K_0$ , the lateral acceleration at which understeer gradient becomes zero,  $a_{VK=0}$ , and the lateral acceleration for incipient jackknife,  $a_{VJK}$ . The tentative, or proposed handling requirement was that the tow car maintain positive understeer gradient up to and including 0.3 g lateral acceleration and that it not jackknife at 0.5 g. It was determined that by limiting the maximum hitch load this requirement could be met or exceeded. Consequently the proposed maximum hitch load versus tow car to trailer weight ratio boundary shown in Fig. 11 was derived. It was the objective of the tests described in this phase to check these boundaries for front wheel drive vehicles.

Fourteen different combination vehicle configurations, plus tow car alone, were tested for understeer gradient using the constant radius circle test procedure. Basically this was done at various hitch loads without load leveling, however one configuration, designed for demonstration only, included load leveling of sufficient magnitude to raise the rear axle of the Citation off the ground. This was done to illustrate how unsafe such a condition would be. Results of these tests are given in Table 8. Individual steer vs. lateral acceleration plots are given in Appendix E. The key conclusions can be summarized as follows:

- All configurations (without load leveling) exhibited positive understeer up to and including 0.45 g.
- All configurations exhibited a decrease in understeer with increasing hitch load.
- Load leveling such as to totally unload the rear axle produced a combination so oversteering that jackknife occurred at 0.1 g cornering!

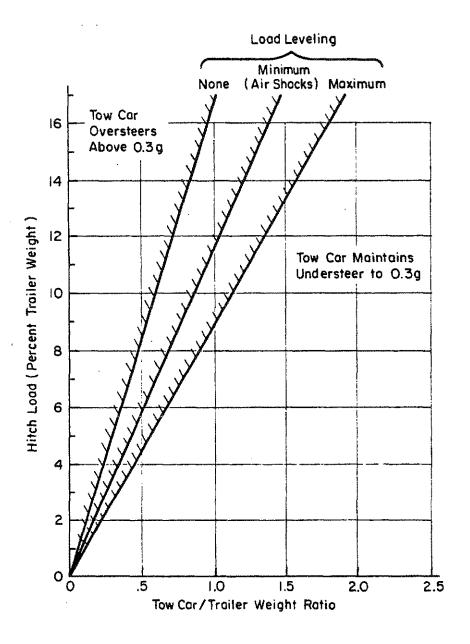


Figure 11. Proposed Maximum Allowable Hitch Load Boundary to Provide Understeering Tow Car up to 0.3 g Cornering (from Vol. II, pg 112)

TABLE 8

TOW CAR UNDERSTEER — CONSTANT RADIUS CIRCLE TEST RESULTS

TOW CAR/ TRAILER	WEIGHT	HITCH LOAD	TOW CAR FRONT/REAR WEIGHT DISTRIBUTION	UNDERSTEER GRADIENT FOR ay < .45 g (deg/g)	STEER GRADIENT,	LATERAL ACCEL., NEUTRAL STEER BYK=0	REMARKS
Citation Alone	3200	0	62/38	5.51	5-19	All > .45	Before trailer testing
				5.80	4.84		After trailer testing
Utility	1500	5	60/40	4.18	3.21		Increasing understeer at 0.40 g
		10	57/43	4.11	2.87		Increasing understeer at 0.40 g
		15	55/45	4.25	2.79		Increasing understeer at 0.35 g
		20	52/48	3.43	2.43		
Camper	1600	10	57/43	5.60	4.04		
Travel	2400	10	54/46	3.79	3.48		Data only to 0.3 g
		0 (+5000 ft- lbs Load Leveling	80/0 (EST)	<i>-</i> 32.	<del>-</del> 32.	0	Rear wheels off ground. Maximum speed on 200 ft circle 17 mph, or .1 g. Demonstration Only.
Horizon	2675		58/42	5.16	4.64		Initial Test
Alone				4.59	-		Test after utility and camper tests
Utility	1500	0	58/42	5.16	5.06		
		5	56/44	5.95	4.63		
	***************************************	10 '	54/46	5.0	3.59		
		15	52/48	4.43	4.01		
		20	50/50	4.40	3.11		was to the same of
Camper	1600	10	54/46	4-19	3.42		
Travel	2400	10	52/48	2.9			Constant speeds and coast down
	ļ			2.83			Continuous speed up
		<u> </u>		2.86			Continuous coast down

The key results have been graphically presented in Fig. 12. It is obvious that, to the extent of the hitch loads that can be practically applied, there is <u>no</u> problem with oversteer or jackknife with the subcompact front-wheel drive cars.

There are two basic reasons for this positive result. First, since FWD cars normally come with 58 to 62 percent of the curb weight on the front axle, the addition of nominal hitch loads never results in more than 50 percent of the tow car weight on the rear axle. Recall from Vol. II that rear drive tow cars achieved an oversteer/jackknife response only when about 60 percent of the tow car weight was on the rear axle. For the two FWD tow cars, the worst case loading (300 lb hitch load) resulted in only 52/48 front to rear weight distribution for the Citation and a 50/50 distribution for the Horizon. The second reason for solid understeer with all configurations is that forward traction applied at the front tires. Knowing how the traction ellipse limits operate, it is easy to see how traction applied at the front wheels will increase understeer. In addition, the bigger the trailer drag load, the more traction is needed at the front wheels.

With regard to the proposed maximum hitch load boundary, Fig. 13 shows that all configurations fall in the allowable hitch load region. To intersect this boundary the Horizon would have to tow the 2400 lb travel trailer at an 18 percent hitch load (or 432 lbs) or load up the utility trailer to 2150 lbs and use a 20 percent hitch load (again a 430 lb hitch load). The Citation would require a 512 lb hitch load to intersect the boundary. Both are far beyond the manufacturer's recommendation and beyond what could practically be applied without scraping the rear bumper on the ground.

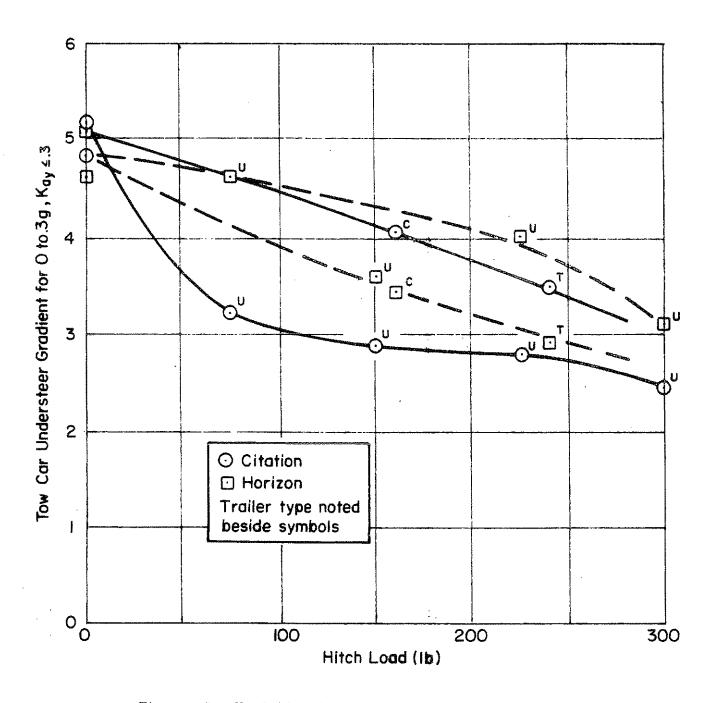


Figure 12. Variation in Tow Car Understeer Gradient with Hitch Load

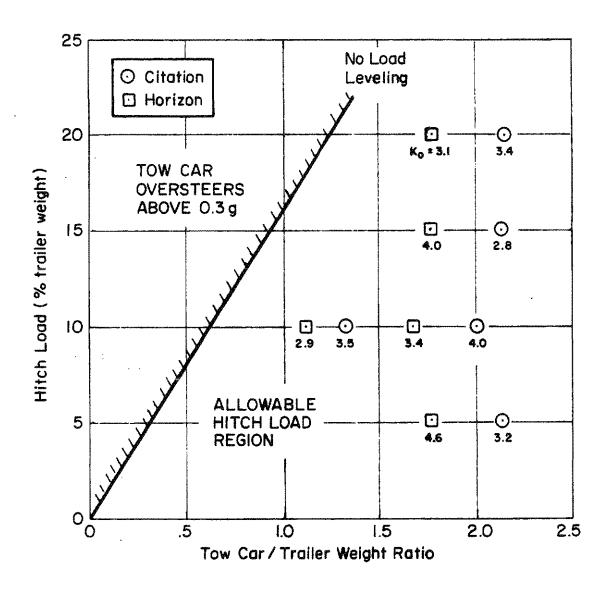


Figure 13. Comparison of Understeer Results with Proposed Maximum Hitch Load Boundary

#### SECTION VI

## COMBINED BRAKING AND CORNERING

The final combination-vehicle test procedure was aimed at uncovering any tow car and/or trailer stability problems during a brake-in-turn maneuver. In Vol. II it was recommended that 0.4 g deceleration during 0.3 g cornering be demonstrated. It was further stated that if the tow car and trailer could meet the previous three requirements (of Sections III, IV, and V) it would be able to perform this brake-in-turn maneuver without transient oversteer tendencies (defined as a yaw rate/speed change of 0.3 deg/sec/mph) for more than one second. Testing in this second phase was to verify this proposed standard for front wheel drive tow cars.

All test runs are identified in Table 9 and 10 for the two tow cars. Results indicated on these tables include stopping distance from 40 mph, average maximum deceleration level,  $a_{\rm Xmax}$ , yaw rate per speed slope,  $\Delta r/\Delta u$ , time duration of yaw rate change, and effective turn radius (computed from peak  $r/u \times 57.3$ ). Ideally the turn radius would remain constant at 355 ft, consequently any transient oversteer tendencies will appear as a tightening of the turn circle, i.e., a reduction in turn radius.

None of the test runs shown in Tables 8 or 9 showed any jackknife tendency or exceeded the transient oversteer requirement. In general, both tow vehicles exhibited front lockup during the maneuver. Iocking this axle (or a wheel on this axle) minimizes any oversteer tendency. However, not all configurations were able to achieve a 0.4 g average deceleration. This occurred for the unbraked trailer combinations and is due to the reduction in tow car deceleration capability in going from straight ahead to a 0.3 g turn. For example, the Citation changed from 0.6 g straight ahead to 0.47 g in a turn and the Horizon changed from 0.68 g to 0.52 g. For the Citation plus utility trailer the deceleration changed from 0.46 g (116 ft) straight ahead to 0.37 in the turn. For the Horizon/Utility combination the reduction was from 0.56 g to only 0.44 g since the tow vehicle alone started with greater capacity. The travel trailer with no brakes also did not make 0.4 g however this could not be achieved even in the straight ahead test.

TABLE 9. BRAKE IN TURN RESULTS FOR CITATION

PEDAL		30 lb	43 1b 37 1b 35 1b 30 1b	332323 332333 3323 3323 3323 3323 3323
LOCK UP	RF RF N Too Low N N N N	LE N N N N	u u Bu ti ti bu bi ti u	E E E E E E E E E E E E E E E E E E E
TURN DIR.	Press Press Press	다 K 다 K 다 K		жкчкчк
RUN NO.	557 159 18 5 5 5 6 8 5 6 8 6 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9	古みひすむる	545448557555	222222 22222 223 233 233
AVG axmax (g)	.476	.378	.39 &	.578
O†lS	108 100 116 117 117 120 120	¥254484	25 25 25 25 25 25 25 25 25 25 25 25 25 2	86.8 106 99.6 86.1 96.9
RMIN (ft)	500	25.7 25.7 20.1	1 1 1 1 1 1 1 1 1 1 1	11111
Δt (sec)	0 0.7 Abort Abort	0.5	111111111	
dr/du (deg/ft)	0000	0.8 0.5 0 0.34	0000000000	00000
HITCH	0	15%	55	\$c \$c
WEIGHT	5200	1500	1600	2400
TRAILER	None	Utility (No Brakes)	Camper (No Brakes)	Travel 100% Brakes
TOW CAR	Citation			

TABLE 10. BRAKE IN TURN RESULTS FOR HORIZON

PEDAL FORCE	87 lb 62 lb 65 lb 67 lb 67 lb 67 lb	70 tb 70 tb 70 tb 70 tb	35° Low 83° S B 83° B 83° B 85° B 85° B 85° B 85° B	88888 88888	85 1b 85 1b
LOCK UP	LLR N N N N N N N N N N N N N N N N N N N	N N N N LF	Press N N BF N N N	N LE BF BF BF BF	BT N
TURN DIR.	нанажака	RLRRLL	инжнжнк	ныгыгы	요 기 .
RUN NO.	<u> </u>	47 48 49 50 51	82885005555	324525	198 199
AVG 8xmax (g)	. 528	8 <del>111</del> .	ड १११	.38 g	.54 g
Offic	87.1 98.3 114 112 103 99.3	123	160 170 170 170 170 122 123 124	142 139 151 144 132	100
RMIN (ft)	185 193 238 - - - 256	1 1 1 1 1 1	278 278 1		l I
Δt (sec)	#.0 4.0 4.0 4.0	11111	0.5	1   4   6	
dr/du (deg/ft)	1.0 1.0 0.7 0 0 0	00000	00.13	00000	00
HITCH	0	15 15 15 15 15 15 15 15 15 15 15 15 15 1	EC C	10%	
WEIGHT	2675	1500	1600	2400	-
TRAILER	None	Utility (No Brakes)	Camper (No Brakes)	Travel (No Brakes)	100% Brake
TOW CAR	Horizon				

37

Based on these results it is not necessarily possible to demonstrate a 0.4 g deceleration during a 0.3 g turn (especially for unbraked trailers) even though the CV can pass the previous three handling and braking requirements. Rather than revising the straight line requirement upward it is recommended that the demonstration test be revised downward from "0.4 g" to a "maximum deceleration (with tow car lock-up) or 0.4 g; whichever occurs first."

#### SECTION VII

### CONCLUSIONS AND RECOMMENDATIONS

This final phase in the development of handling and braking standards for passenger cars towing trailers has tested two front wheel drive subcompacts plus three nominal trailers in over 30 combination vehicle configurations. Results have verified and revised the previous results and recommendations, especially with regard to unbraked trailers. In fact, the front wheel drive vehicles make better tow cars than their rear wheel drive counterparts. This is due to their nominally high front weight bias which becomes more evenly distributed when a hitch load is added. This improves braking, tow car stability, and trailer swing.

This section reviews the suggested handling and braking criteria and means for insuring compliance presented in Vol. II and shows how conservative these boundaries will be for front wheel drive tow cars. In addition, an integrated handling standard is derived for the three trailers tested in this phase. Plots such as these can be derived by trailer manufacturers and are recommended for each trailer model as a means for implementing the proposed standards.

#### A. HANDLING AND BRAKING PERFORMANCE CRITERIA

The following performance criteria were previously recommended for passenger car/trailer combinations:

- All combination-vehicles shall be capable of stopping within 134 ft from 40 mph, i.e., average deceleration of 0.4 g.
- All trailers of a combination shall exhibit a minimum trailer swing damping ratio of 0.15 (i.e., 3/4 cycles to one-half amplitude) at 55 mph.
- All tow cars of a combination shall exhibit a positive understeer gradient up to and including 0.3 g cornering.
- All combination-vehicles shall demonstrate 0.4 g deceleration during 0.3 g cornering without incurring transient oversteer (increased yaw rate) for longer than 1 sec duration.

All these requirements can be met by proper selection of a trailer for a given tow car size (i.e., weight) and proper setting of hitch load.

#### B. MEANS FOR INSURING COMPLIANCE

The above requirements can be insured by specifying a tow car to trailer weight ratio as a function of trailer brake capacity (for braking tests) and of hitch load (for handling tests). Each is discussed below.

## 1. Braking

The primary problem that will occur in meeting the straight-line brake and brake in turn requirements is specifying the tow car weight necessary for unbraked trailers. This occurs because some states allow unbraked trailers up to 3000 lb. For example, it was recommended in Phase I, for rear wheel drive tow cars, that the tow car be a minimum of 2.1 times the trailer weight. In this phase we have determined that for front wheel drive cars this multiplier can be reduced to 1.5. This value definitely represents a lower bound since it represents optimum brake force at both front and rear. If we hope to meet (or exceed) a 0.4 g CV deceleration requirement with all tow vehicles, the 2.1 value represents a more conservative recommendation. However, even assuming the more optimistic value of 1.5, the 3000 lb unbraked trailers would have to be towed by at least a compact sized vehicle (GVWR \geq 4500 lbs). If such a restriction is not possible, the overall stopping distance requirement will have to be relaxed. This would, however, be inconsistent with the stopping capability of braked trailer combinations.

For braked trailers the recommended tow car to weight ratio selected above can be reduced by a factor of 3.5 times the "trailer-alone" braking capability (in g units), i.e.,

$$\frac{W_c}{W_t} \ge 1.5 - 3.5 a_{xta}$$

Current contemporary trailer manufacturers are providing 0.43 g capability, and test results from both phases showed 5 out of 7 trailers (with brakes)

exceeding this value. Only when the trailer weight exceeded 1500 lbs per each 2"  $\times$  10" brake did a trailer not meet 0.43 g. Assuming this trailer design criteria there would be <u>no</u> restriction on minimum tow car weight.

## 2. Handling

Trailer and stability can be insured by specifying a minimum hitch load boundary as a function of the tow car to trailer weight ratio for <u>each</u> trailer model. A different model would be defined as a change in weight, effective tongue length, tires, and/or moment of inertia. Methods have been presented in Vol. II, in Ref. 3, and by the Recreational Vehicle Manufacturers Association (RVIA) to analytically derive this boundary. However, some full scale CV tests are necessary to properly coalesce the analytical and emperical results. Front wheel drive cars will have a lower tow car sensitivity factor than rear wheel drive tow cars.

Tow car stability can be insured by specifying a fixed maximum hitch load boundary as a function of tow car to trailer weight ratio, for various values of load leveling. Three values have been illustrated; none (using air shocks only) minimum (based on using air shocks to their fullest and then adding leveling torque as necessary to relevel the CV), and maximum (based on no air shocks and leveling torque such as to transfer 25 percent of the hitch load to the front axle). Based on results presented in this volume, front wheel drive tow cars will find these boundaries somewhat conservative.

Combining the trailer and tow car stability boundaries results in an integrated handling compliance plot for each trailer. Figure 14a, b, and c show examples of this format for the three trailers tested in this phase. Note that the minimum tow car size is equal to greater than the trailer weight; a good rule of thumb. Also, the front wheel drive tow cars allow a lighter hitch load than an equal weight front wheel drive car. In either case the optimum hitch load for the minimum weight tow car is about 15 percent. This figure is another common rule of thumb. Increasing the tow vehicle weight rating quickly opens up the allowable hitch load region. This consistency implies a proper selection of the performance criteria.

Although the trailer examples presented in Fig. 14 give a good overall picture of the tow car/trailer tradeoffs, application by a user probably

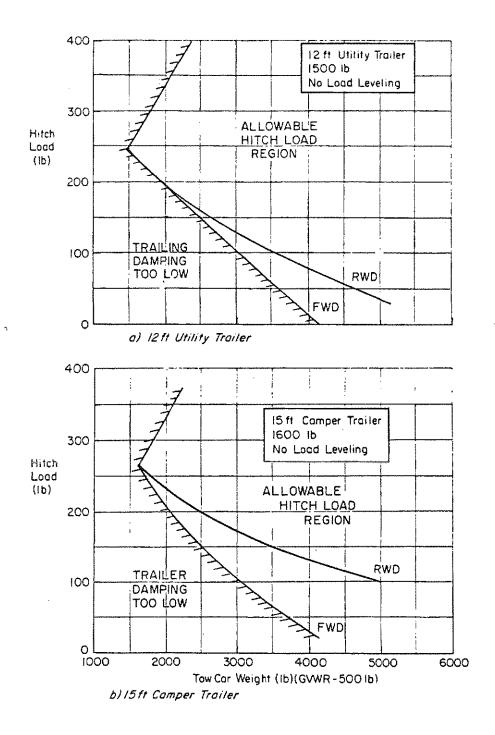
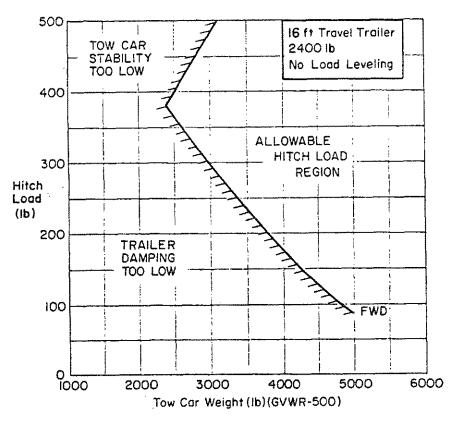


Figure 14. Recommended Integrated Trailer Handling Standard Examples



c) 16 ft Travel Trailer

Figure 14. (Concluded)

always will start with a specific tow car. In this case, the upper hitch load limit may be dictated by the tow car manufacturer due to limitations of power, cooling, structure, etc. Generally, the manufacturer's limit will occur prior to reaching the stability limit. For example, many subcompacts recommend hitch loads no more than 100 lb; whereas Fig. 14 would allow up to 400 lb. In short, manufacturers' maximum hitch load recommendations should always take precedence.

# 3. Handling and Braking

No additional handling requirements appear necessary in order to meet the brake in turn performance requirements. However, unbraked trailers weighing more than 67 percent of the tow car cannot decelerate at a 0.4 g average. Since tow car lockup determines the transient tow car stability change it is recommended that if the CV cannot decelerate at 0.4 g, the test be conducted at the maximum deceleration with lockup of one wheel on one axle permitted. In effect, the combined handling and braking performance criteria stated previously should be changed to read:

All combination-vehicles should demonstrate maximum deceleration (with tow car lockup) or 0.4 g deceleration (whichever occurs first) during 0.3 g cornering, without incurring transient oversteer for longer than 1 sec duration.

If additional tests are conducted with passenger cars that exhibit rear wheel lockup (in straight ahead braking) it is recommended that they be tested with minimum hitch load trailers in order to represent the worst case condition. Previously, with front wheel lockup tendency, the maximum hitch load configurations (with no trailer brakes) represented the worst case.

# REFERENCES

- 1. Klein, Richard H., and Henry T. Szostak, Effects of Weight Distributing Hitch Torque on Car/Trailer Directional Control and Braking, DOT HS-803 248, Oct. 1977.
- 2. "Car/Trailer Handling Standards Development," NHTSA Contract DOT-HS-7-01720, 27 September 1977.
- 3. Klein, Richard H., and Henry T. Szostak, "Determination of Trailer Stability Through Simple Analytical Methods and Test Procedures," SAE Paper 790186, in <u>Dynamics of Wheeled Recreational Vehicles</u>, SAE SP-443, Feb. 1979, pp. 47-53.

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## APPENDIX A

# TOW VEHICLE AND TRAILER SPECIFICATIONS

This appendix contains all the relevant specifications, measured parameter values, and vehicle equipment descriptions for the two tow vehicles and three trailers used in this final test program phase. These data are presented in Tables A-1 and A-2, respectively.

Individual tow car and trailer braking test results are presented in Fig. A-1 for the Horizon, Figs. A-2 and A-3 for the surge brake gain of the camper trailer, and Fig. A-4 for the electric brake travel trailer.

Since several questions have come up regarding trailer roll-steer effects, the roll steer coefficient of the travel trailer was determined in Fig. A-5 to be 0.3 deg/deg.

TABLE A-1. TEST VEHICLE SPECIFICATIONS

SPECTPTC1TTCVS	TOW CARS						
SPECIFICATIONS	DOWN-SIZED COMPACT	SUB-COMPACT					
Vehicle	1979-1980 Chevrolet	1979 Plymouth					
, 5,, 2,2,2	Citation	Horizon					
	4 Door Sedan	- Door Sedan					
GWR	3571 lb	3115 lb					
Front	2000 15	1700 15					
Rear	1571 lb	1465 15					
Vehicle Cargo Capacity	895 26	715 16					
Passengers	5 Passengers	4 Passengers					
Trunk	150 lb	115 16					
Curb Weight							
Front Rear	1740 lb	1425 16					
near Total	990 lb 2730 lb	875 1b 2300 1b					
Test Weight (including driver but without hitch head)	2						
Front	1935 lb	1560 lb					
Rear	1200 lb	1115 lb					
Total	3135 lb	2675 lb					
Tire Make	Uniroyal Fastrak Redial	Firestone Deluxe Champion Radia:					
Size	P 185/80 R 13	P155/80 R 13					
Nom Pressure	26 psi	29 psi					
Load range	B	B					
Load capacity	1301 lb at 35 psi	959 lb at 35 psi					
Construction of Casing	2 ply Fiberglass Belts 1 ply Polyester	2 ply Fiberglass Belts					
Rim Width	5.5"	1 ply Polyester 4.5"					
-							
Steering Type	Saginaw Power Boosted Rack and Pinion	Saginaw Power Bocsted Rack and Pinion					
Overall ratio	17.5	18.0					
Hysteresis with	±2,25 deg	±2.25 deg					
no load (at	1	, 3					
steering wheel)							
Wheelbase, £	104.9"	99.2"					
Overhang to ball	1.8"	35"					
hitch, sh	-0						
Wheel Track, Front	58.7"	55.5"					
Rear	57.0"	55-1"					
Front Suspension	Macpherson Struts Lower A-Arms	Macpherson Struts Lower A-Arms					
	The state of the s						
Springs	Coil	Coil					
Anti Roll Ber	Yes	Yes					
Rear Suspension	Beam axle on trailing arms,	Semi-independent trailing					
D=== 4 == == in	plus Panhard Rod	arms .					
Springs Anti Roll Bar	Coil Yes	Coil					
WILL YOLL DEC	res	Yes, via beam interconnection of trailing arms					
Fear Chock Absorbers	Delco "Air Lift"	No Air Shocks available					
Added for Hitch Load Capacity		WO WIT PROCES SASITABLE					
Brakes	Vacuum Boosted	Manual Operated					
Front	Disc	Disc					
Rear	Drun	Drum					
Engine and	173 C.I.D. V-6	105 C.I.D. 4 Cylinder Engine					
Transmission	Automatic Transmission	Automatic Transmission					

TABLE A-2. TEST TRAILER SPECIFICATIONS

			WEIGH	HT SPECIA	CICATION	S	BRAKES	
TYPE	MFG. MODEL	EMPTY	TEST	GVWR	GAWR	HITCH LOAD	MFG./SIZE/ACTUATION	
Utility	U-Haul 5 × 8 3533AV3894	920	1500	5600	UNK	10 Percent	None	
Camper	Starcraft Starmaster 6 1977	1430	1600	2090	2090	180 to 300 curb maximum	Bendix, Drum, Surge 7 × 1.75	
16 Ft Travel	Cal-Camp. Mustang 1510	2200	5400	- 5400-	3000		Kelsey Hayes 10 x 2 in. Drum, Electric	

# a) Weight and Brakes

TYPE	WHEELBASE, £2, AXLE & TO BALL HITCH	LENGTH BETWEEN TANDEM AXLES	TRACK WIDTH	TRAILER BOX LENGTH × WIDTH	TONGUE WIDTH	OVERALL HEIGHT	FLCOR TO GROUND HEIGHT	OVERALL DENOTE
Utility	92''	NA.	75"	94" × 60"	41"	81.5"	15.5"	11'-6"
Camper	125"	NA	56.375"	124.5" × 80"	50"	53.5"	15.5"	15'-3"
16 Ft Travel	140.5"	NA	66"	159" × 80"	33"	99"	20"	16'-4"

# b) Geometry

			TIR	28			
TYPE	MFR., MODEL	SIZE	RATED LOAD CAPACITY	CASING CONSTRUCTION	REC. WHEEL RIM PRESS. WIDTH		SUSPENSION TYPE
Utility	Goodyear U-Haul Traction Hi-Miler	670-15UT	"C" 1530 lb at 45 pai	Bias 4 ply nylon	45 psi	5.25"	Solid beam axle Leaf springs Compression shackles
Chaper	Goodyear HI-Lander CT	1	"C" 1045 lb at 80 psi	Bias ply	80 psi		Solid beam axle Leaf springs
16 Ft Travel	Bridge- Stone	7:00 × 14	"C" 1430 lb at 36 psi	4 ply Polyester 2 ply nylon belt	36 psi	5.0"	Solid beam axle Leaf springs Compression shackles

# c) Tires and Suspension

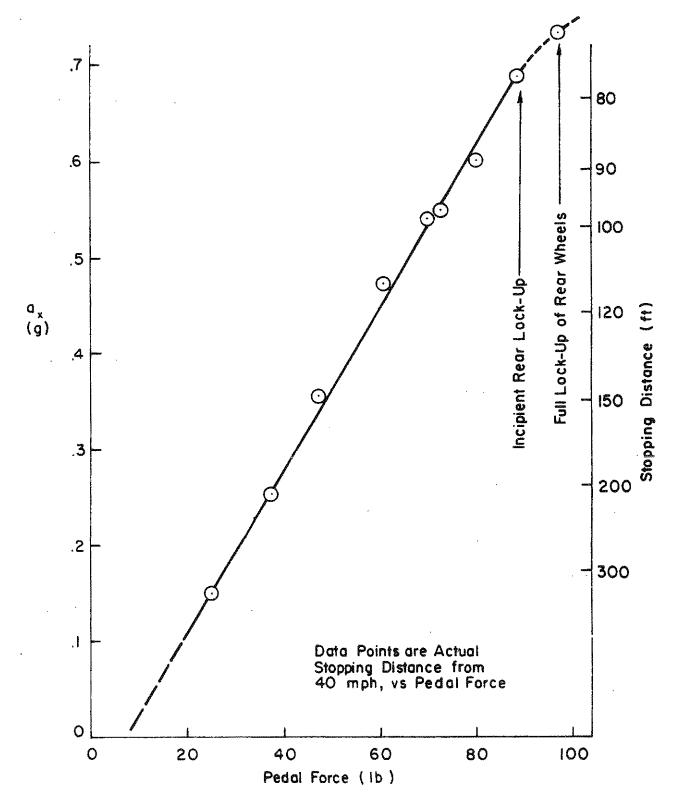


Figure A-1. Plymouth Horizon Brake Gain Test Data Run Nos.: 124-132

Trailer: Camper Test Wgt: 1600 lb Axle Load: 1440 GAWR: 2090

Hitch Load: 10% (1601b) Data Run No. 136 - 142

Brake Type: Bendix Surge Brakes

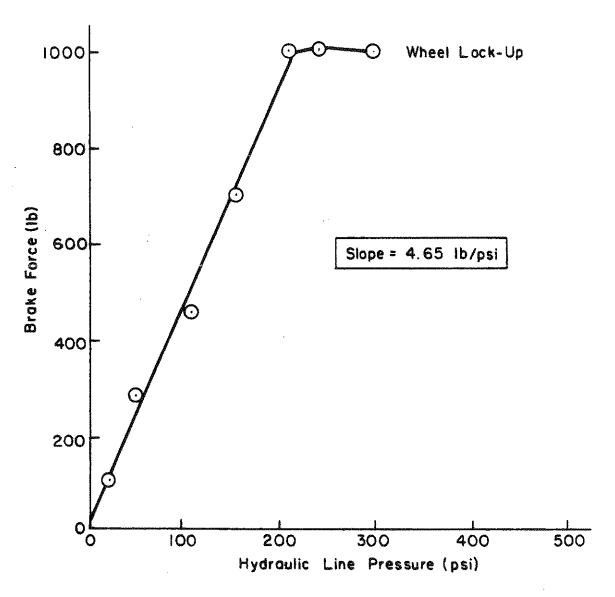


Figure A-2. Brake Force vs. Hydraulic Line Pressure for Surge Brake Trailer

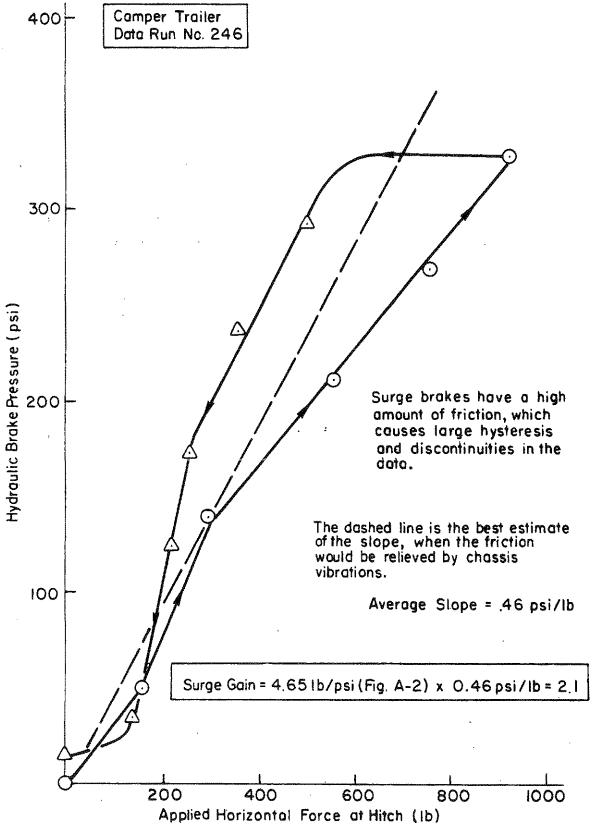


Figure A-3. Hydraulic Brake Pressure vs. Applied Horizontal Hitch Force for Surge Brake Trailer

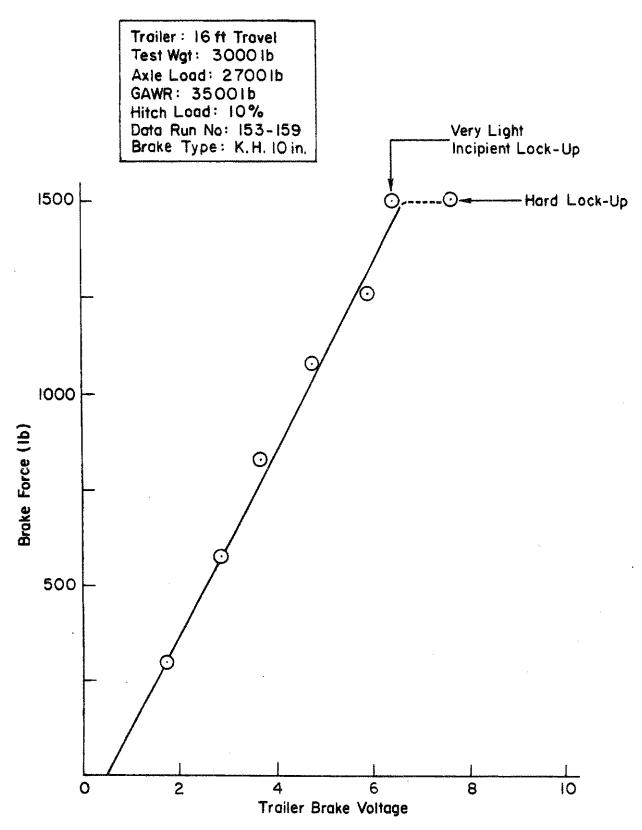
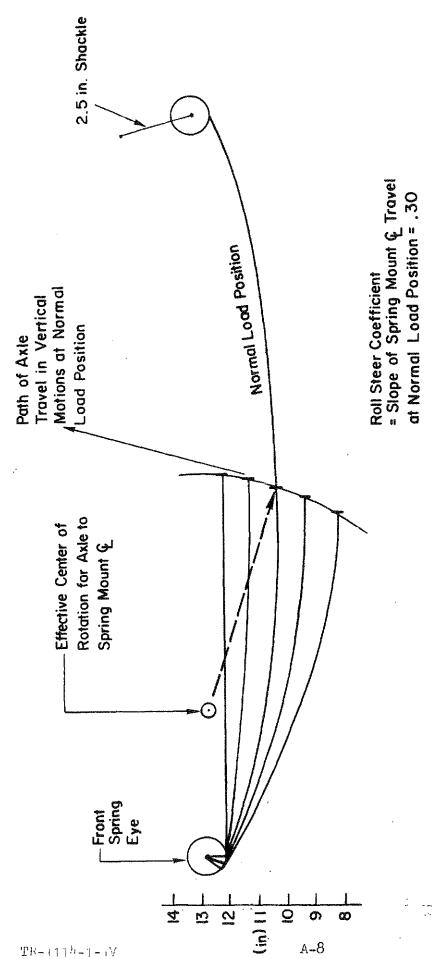


Figure A-4. Brake Force vs. Applied Trailer Brake Voltage for 16' Travel Trailer



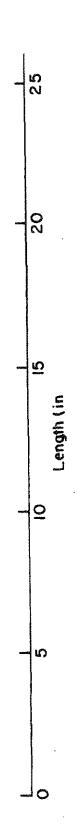


Figure A-5. 16' Travel Trailer Leaf Spring Suspension Geometry as Measured on Test Trailer

TR-+174-1-1V

## APPENDIX B

# RUN LOG SUMMARY '

This appendix contains a complete listing of all tests recorded on FM tape. Tables B-1 and B-2 detail the exact run numbers associated with each test. These run numbers can then be associated with tape footage numbers on two FM tapes by reference to the raw run logs kept with the FM tapes. A description of the FM tapes (i.e., sensors, scale factors, center frequency, etc.) was given in Vol. III, Appendix B.

TABLE B-1. CITATION TEST RUNS

TRAILER	PERCENT HL	SLB	OTHER	BIT	PST	CRT
None Car-Alone		1-10	**************************************	12-20		11, 21 Low Gain
U-HAUL						
1000 lb	10	22-35			36 <b>-</b> 39	
1500 lb	20				· · ·	40
1500 lb	15	47 <b>-</b> 52		416-46	53 <b>-</b> 57	41a
1500 lb	10	61 <b>-</b> 67			58 <b>-</b> 59	68
1500 lb	5	70 <b>-</b> 78			79 <b>-</b> 80	69 Low Gain
1500 lb	0	85-91		-	81-84	
2600 lb	10	96 <b>-</b> 104			92 <b>-</b> 95	
CAMPER 1600 lb	15		:	-	105-106	
- Company of the Comp	10	112-121	136-142 (BTA)		108-111	107
4	5				122-123	
***************************************	0	-		1	124-126	
No Brakes	10	127-135		143-153 Low Gain		
No Brakes Rerun	10	154-161				
U-HAUL 1500 lb Rerun	10	162-172		The contraction of the contracti		
TRAVEL 2400 lb	10		173-183a (BTA)		186-191	183b-185 Low Gain
100% Br.	10	,214 1201 <b>-</b> 205		215-220		
0% Br.	10	192-200				
50% Br.	10	206-213				
	5				227-231	
	15				224-226	
None Car Alone		232-241				243 Low Gain
Surge Br. Gain			246(BTA)		-	
Wheels Off Gr. + T.T.						247

TABLE B-2. PLYMOUTH HORIZON TEST RUNS

TRAILER	PERCENT HL	SLB	OTHER	BIT	PST	CRT
None Car-Alone		1-11	(Br. Gain) 124-132	12-19		20 (Hi Gain) 133 (Low Gain)
U-HAUL						
1500 lbs	20					35 (Hi Gain)
	15	36-44		47-52	45-46	53 (Low Gain)
	10	54 <b>-6</b> 0			61-63	64 (Low Gain)
	5				66-68	65 (Low Gain)
	0	74-82		and de service and de	69 <b>-</b> 72	73 (Low Gain)
U-HAUL		· · · · · · · · · · · · · · · · · · ·				
2600 lb	5			dereite de	203-204	
42	10	86 <b>-</b> 95			83-85	
CAMPER						
1600 lb	15			96~104	105-106	
	10	109-114	(SLB.6g		107-108	115 (Low Gain)
,		134-146	Tow Car)			,
	5	154-140	147-152	fishering.	116-118	
	0				119-123	
	-				119-12)	
TRAVEL		<b>7</b>				
3000 lb	10	(BTA) 153 <b>-</b> 159				
TRAVEL						
2400 lb	15				160-162	
·	5				163-167	
	10	168-176	(.6 g T.C. and 100% T.T. Br. SLB) 177-182	192 197 Note	189-191	200 Step Sp. and Coast- Down
	10		(.6 g T.C. No T.T. Br. SLB) 183-188	198-199 100% TB		201 Contin. Sp. and Coast-Down

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## APPENDIX C

# STRAIGHT LINE BRAKE TEST DATA

Table C-1 and C-2 present all tow vehicle alone and combination vehicle data for the Citation and Horizon, respectively.

TABLE C-1. STRAIGHT LINE BRAKE DATA FOR CHEVROLET CITATION

				COND	ITIONS				
RUN NO.	TOW VEHICLE	TRAILER	WEIGHT	HITCH LOAD	LOAD LEVELING	PEDAL FORCE	LOCK-UP	SD40	AVG ± STD. DEV.
2345	Citation Alone (3200 lbs) Before CV Tests	None	3200			45 57 50 51 53 53 57	NO RF NO NO NO NO NO LF RF	98.9 93.1 94.3 85.9 84.8 85.4 87.9 82.1 86.1	Press too low 88.0 ± 4.1 86.9 ± 4.0 (No Lock-Up)
233 234 235	After CV Tests	None	3200			50 50 70 65 65 65 65 65 65 65	NO BF NO NO LF LF LF	116 90.7 86.9 84.4 92.2 93.1 96.1	Press too low 90.6 ± 4.3
22 23 24 25 26 27 28 29 30 31 32 33 34 35		U-Haul	1000	10	NO	48 48 50 55 40 40 40 40 40 33 5 38 38	NO NO BF RF INC. NO BF LF NO NO NO NO	118 101 107 113 106 101 107 108 109 Abort 102 Abort 112 98.4	107 ± 5.7 106 ±7.5 (No Lock-Up)
47 48 49 50 51 52			1500	15	NO	38 35 37 44 40 38	NO NO NO BF BF BF	118 117 115 117 127 123	120 ± 4.5 117 ± 1.5 (No Lock-Up)

TABLE C-1. CONTINUED

				COND	ITIONS				4.1.0
RUN NO:	TOW VEHICLE	TRAILER	WEIGHT	HITCH LOAD	LOAD LEVELING	PEDAL FORCE	LOCK-UP	SD4O	AVG ± STD. DEV.
61 62 63 64 65 66 67		U-Haul	1500	10	NO	40 38 × 38 40 40	NO NO NO NO NO	124 116 Abort 110 116 114	116±4.6
162 163 164 165 166 167 168 169 170 171	Sw	un Same (itched F:	ront/Re			40 47 47 55 58 67 73 65	NO NO NO NO NO NO NO BF BF RF	120 115 114 115 113 111 109 111 119 117 Abort	114 ± 3.6 114 ± 3.4 (No Lock)
70 71 72 73 74 75 76 77		U-Haul	1500	5	NO	40 37 37 40 37 42 42 45	NO NO NO NO NO NO NO RF	120 Abort 115 114 120 118 Abort 115 118	117 ± 2.5 117 ± 2.7 (No Lock)
85 86 87 88 89 90	5  7  8  9		1500	0	NO	400000000000000000000000000000000000000	NO NO NO NO NO NO RF	Abort 108 112 113 110 112 116	112 ± 2.7 111 ± 2.0 (No Lock)
96 97 98 99 100 101 102 103	7 3 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9		2600	10	NO	43 35 33 32 30 30 30 35 30	RF RF NO NO NO NO NO	143 145 Abort Abort 158 157 158 161 163	155 ± 7.8 159 ± 2.5 (No Lock-Up)

TABLE C-1. Continued

				COND	ITIONS				100
RUN NO	TOW .	TRAILER	WEIGHT	HITCH LOAD	LOAD LEVELING	PEDAL FORCE	LOCK-UP	SD40	AVG ± STD. DEV.
112 113 114 115 116 117 118 119 120 121		Camper with Surge Brakes	1600	10	NO	45 38 35 30 33 35 33 33 40	BF NO BF NO NO NO NO NO BF	111 113 116 Abort 115 112 112 113	113 ± 1.6 113 ± 1.2 (No Lock-Up)
127 128 129 130 131 132 133 134 135		Camper No Brakes	1600	10	NO	42 43 43 35 35 37 33 42	NO RF RF NO NO NO NO	121 128 126 121 128 132 137 Abort 118	126 ± 6.3 126 ± 7.4 (No Lock-Up)
154 155 156 157 158 159 160 161		run Same Front/Re- Swit	ar Tire			40 40 40 50 50 45 43 52	NO NO NO NO NO NO RF	135 124 120 120 123 120 119 120	123 ± 5.3 Same/No Lock-Up
201 202 203 204 205 214		16' Travel	2400 Full Brakes	10		× 37 37 38 35 37	NO LF,LT BF,BT BF,RT BF,RT RT	Abort 97.7 97.0 97.3 96.9	98 ± 1.7 Including Lock-Up
206 207 208 209 210 211 212 213		16*	58% Brakes (700 1b)	10		37 36 35 38 37 36 37 35	NO -	121 Abort 114 111 Abort 118 108	114 ± 4.9

TABLE C-1. CONCLUDED

				COND	ITIONS				
RUN NO.	VEHICLE TOW	TRAILER	WEIGHT	HITCH LOAD	LOAD LEVELING	PEDAL FORCE	LOCK-UP	SD40	AVG ± STD. DEV.
192 193 194 195 196 197 198 199 200	Citation	16' Travel	No Brakes	10		37 45 50 47 40 40 40	no lif bf rf	146 139 143 149 141 133 146	141 ± 6.0 138 ± 5.3 (No Lock-Up)

TABLE C-2. STRAIGHT LINE BRAKE DATA FOR PLYMOUTH HORIZON

	RUN NO.	TRAILER WEIGHT	HITCH LOAD %	PEDAL FORCE	LOCK- UP	SD40	AVERAGE OF BEST SIX	TEST RUN STOPPING DISTANCE NOT USED
A CONTRACTOR OF THE PROPERTY O	1 2 3 4 5 6 7 8 9 10 11	None Car Alone Before CV Tests	·	32.5 57.5 70 85 95 95 97.5 92.5 92.5	LR LR	220 115 94 84 78.7 81.2 79.7 82.9 76.9	79•33 ±2•45	Brake Pressure Too Low
	23 24 25 26 27 28 29 30 31 32 33 4	U-Haul (1000 lb)	10	65 80 75 85 95 102.5 102.5 105 100 107.5	LR,RR	159 122 109 101 90.95 89.8 86.85 89.0 85.45 86.9	88.16 ±2.09	Brake Pressure Too Low
	36 37 38 39 41 42 44 44	U-Haul (1500 lb)	15	100 102.5 100 100 97.5 92.5 95 95 92.5	RF RF RF	110 	99.34 ±1.18	Initial Run Brake Action Released Inconsistant Run
	54 55 56 57 58 59	U-Haul (1500 lb)	10	95 95 95 95 100 97•5 102•5	LF	102 99.6 94.6 95.2 97.5 98.6 92.3	96.30 ±2.75	Initial Run

TABLE C-2. Continued

RUN NO.	TRAILER WEIGHT	HITCH LOAD %	PEDAL FORCE	LOCK- UP	SD40	AVERAGE OF BEST SIX	TEST RUN STOPPING DISTANCE NOT USED
74 75 76 77 78 79 81 82	U-Haul (1500 lb)	0	* 80 80 80 80 80 85 80	LR,RR	CV 116 116.5 113.8 115.5 117.5 116.6	115.38 ±1.93	Jack Knifed  Inconsistent Run
86 87 88 89 91 93 94 95	U-Haul (2600 lb)	10	80 80 85 90 90 90 95 97.5 92.5	LF,RF	126.7 129.0 127.7 127.7 128.3 127.8	127.87 ±0.76	Low Brake Pressure  No Brake Action  Inconsistent run
109 111 111 111 111 113 113 113 113 114 114	Camper (1600 lb) No Brakes	10	85 90 90 90 90 90 Rerun 85 85 95 100 100 105 105 105 100 100	LR LF	113 110 113 109 113 112 No Act. 122 108 108 105 100.7 100.7 100 95.8 93.3 97.6 99.33	97·79 ±2.82	Brake Pressure Too Low  No Brake Action  Inconsistent Run

<sup>\*</sup>No Force on paper.

TABLE C-2. Concluded

RUN NO.	TRAILER WEIGHT	HITCH LOAD	PEDAL FORCE	LOCK- UP	SDI <sub>IO</sub>	AVERAGE OF BEST	TEST RUN STOPPING DISTANCE NOT USED
147 148 149 150 151 152	Camper (1600 lb) No Brakes .6 g Tow Car	10	82.5 85 85 85 85 87.5		117.05 118.2 117.36 117.74 120.1 115.65	117.68 ±1.47	
168 169 170 171 172 173 174 175 176	Travel Trailer (2400 lb) 100% Brakes	10	92.5 102.5 95 100 97.5 97.5 95 95	RF RF	87 84 82.0 78.3 80.6 77.8 77.3 80.6	79.43 ±1.89	Low Brake Pressure Inconsistent Run Inconsistent Run
177 178 179 180 181 182	Travel Trailer (2400 lb) 100% Brakes .6 g Tow Car	10	80 82.5 85 85 85 87.5		87.7 82.6 87.1 91.5 83.95 88.3	86.86 ±3.19	
183 184 185 186 187 188	Travel Trailer (2400 lb) No Trailer Brakes .6 g Tow Car	10	80 80 80 82.5 80 75		134.9 138.9 137.2 136.4 139.8 136.1	137.22 ±1.83	

#### APPENDIX D

## TRAILER DAMPING RATIO DATA

This appendix presents individual pulse steer test results for all combination-vehicles. Table D-1 presents the Citation tests and D-2 the Horizon tests. Both damping ratio ( $\zeta$ ) and natural frequency ( $\omega_n$ ), in radians/sec are given. The four run average was used in deriving the trends presented in Section IV The individual test data were derived by fitting a pure second order system to the measured hitch angle response. Examples of this fitting procedure are shown in Fig. D-1 through D-4 for the Horizon/Utility trailer at 0, 5, 10, and 15 percent hitch loads respectively.

TABLE D-1. COMBINATION-VEHICLE DAMPING RATIO RESULTS WITH CHEVROLET CITATION

	TRAILER	HITCH	RUN	SPEED			AVE	RAGE
TRAILER	WEIGHT	LOAD (%)	NUMBER	(MPH)	ζ	ωn	ζ	ω <sub>n</sub>
Utility	1000	10	36 37 38 A B C D	55 55 55 55 55 55	.375 .248 .405 .321 .356 .256	5.76 7.15 6.42 5.92 6.21 6.24	.327	6.28
			39	45	.343	6.17	.343	6.17
	1500	15	54 A B C D	55 - 55 - 55 - 55	.324 .287 .246 .198	6.47 6.26 5.31 5.95		
			55	45	.442	6.88		
	And the second s		56 A . B	35 35	.382 .431	7.71 7.46	.407	7-59
			C	45 45	•357 •473	7.48 7.47	.424	7.28
			57 A B	55 55	.258 .589	7.49 5.75	.317	6.21
		10	58 A	35	.320	4.02	.320	4.02
			В	45	.274	7.10	.274	7.10
	In the state of th		59 B C D	55 55 55	.28 .25 .21		.25	
		5 .	79 A B	35 35	.301 .420	4.69 5.65	.361	5.17
			C D	45 45	.266 .243	5.97 4.75	.255	5.36
			80 A B C D	55 55 55 55	.252 .132 .096 .113	4.52 5.34 6.15 5.74	.148	5.44

TABLE D-1. CONTINUED

	TRAILER	нтсн	RUN	SPEED			AVEF	RAGE
TRAILER	WEIGHT	LOAD (%)	NUMBER	(MPH)	ζ	$\omega_{ m n}$	ζ	ω <sub>E</sub>
Utility	1500	0	81 A B	35 35	. 203 . 105	5.08 5.18	•15 <sup>4</sup>	5 <b>.1</b> 3
			82 A B	45 45	.128 .104	5•27 5•35	.116	5.31
			C 83 A B 84	55 55 55 55	.071 .087 .065 .083	5.47 5.35 5.81 5.42	.076	5 <b>.51</b>
	2600	10	92 A B C D	35 35 35 35	.248 .466 .302 .360	5.21 4.90 5.52 5.37	.344	5.25
			E F	45 45	.346 .342	5.30 5.11	. 244	5.21
			93 A B C D 94 A B C D 95 A B	55 55 55 55 55 55 55 55 55 55	.183 .189 .212 .153 .178 .167 .199 .161 .183 .205	5.55 5.34 5.40 5.45 5.17 5.17 5.19	.183	5.40
Camper	1600	15	105 A B	<b>3</b> 5 <b>3</b> 5	·572	4.61 5.01	.511	4.81
		· ·	C D E F	45 45 45 45	.296 .352 .361 .330	5.13 4.85 4.37 4.69	.335	4.76
			106 A B C D	55 55 55 55	.253 .276 .292 .275	5.01 4.95 4.36 4.75	.274	4.77

TABLE D-1. CONTINUED

	TRAILER	нгтсн	RUN	SPEED	_		AVEF	RAGE
TRAILER	WEIGHT	LOAD (%)	NUMBER	(MPH)	ζ	ωn	ζ	ωn
Camper	1600	<b>1</b> 0	108 A B C	35 35 35	•291 •355 •304	5.35 4.84 4.89	.321	4.85
ACCUMANTAL AND ACCUMA			D E F 109 A B C 110 A B C D E F G	44444444444444444444444444444444444444	.286 .247 .207 .250 .250 .254 .295 .258 .258 .254 .254 .236	4.50 4.76 4.51 4.51 4.50 4.50 4.50 4.50 4.50 4.40	. 248	4.53
			н	35	.388	4.45		
	A TOTAL AND		111 A B C D	55 55 55 <b>5</b> 5	.182 .211 .177 .191	4.65 4.38 4.56 4.32	.190	4.48
		5	122 A B C D	35 35 35 35 35	.250 .211 .242 .242	4.41 4.88 4.36 4.50	.236	4.54
			E F	45 45	.167 .199	4.44	.183	4.43
		-	123 A B C D	55 55 55 55	.142 .151 .149 .131	4.28 3.83 3.97 4.10	.143	4.05
		0	124 A B C D	35 35 35 35 35	.199 .154 .349 .221	4.34 4.26 4.26 4.45	.231	4.33
			E F G	45 45 45 45	.120 .116 .105	4.25 4.25 4.21	.114	4.24

TABLE D-1. CONCLUDED

	TRAILER	нгтсн	RUN	SPEED			AVER	AGE	
TRAILER	WEIGHT	LOAD (%)	NUMBER	(MPH)	ζ,	ω <sub>n</sub>	ζ	ω <sub>n</sub>	
Camper (Cont)	1600	0	125 A B 126 A B	55 55 55 55	.081 .060 .062 .043	3.95 3.93 4.20 3.87	.062	3.99	
Travel	2400	10	186 A B	35 35	.281 .271	4.06 3.94	.276	4.00	
			C D	45 45	.209 .176	3.50 4.14	.193	3.82	
			187 A B 188 A B C D E 189 A B 190 A B C 191 A B	55 55 55 55 55 55 55 55 55 55 55 55 55	.114 .137 .129 .142 .119 .145 .195 .148 .112 .156 .137 .086 .198	4.01 4.00 4.01 4.16 4.16 4.17 4.17 4.17 4.17 4.17 4.17 4.17 4.17	.138	3.96	
		5	224 A	35	.318	4.21	.318	4.21	
	The state of the s		B C D	45 45	.201 .266	4.19 3.67	.234	3.91	
			5	225 A B 226 A B C	55 55 55 55 55	.178 .219 .184 .250 .253	4.18 3.62 4.11 3.81 3.81	.217	3.91
				227 A B C D	35 35 35 35	•177  •195 •217	4.14 	.196	4.31
			228 A B	45 45	.163 .167	3.72 3.70	.165	3.71	
			229 230 A B C 231 A B C	55 55 55 55 55 55 55	.094 .154 .141 .082 .065 .083 .064	4.11 3.85 3.97 4.04 3.84 3.76 3.86	.098	3,92	

TABLE D-2. COMBINATION VEHICLE DAMPING RATIO RESULTS WITH PLYMOUTH HORIZON

	TRAILER	нтгсн	RUN	SPEED			AVE	RAGE
TRAILER	WEIGHT	LOAD (%)	NUMBER	(MPH)	ζ	ωn	ξ	Φ'n
Utility	1000	10	21 A B	<b>3</b> 5	.251 .261	6.63 6.85	.256	6.74
			C D	45 45	.187 .175	6.76 7.00	.181	6.88
			22 A B C D	55 55 55 55	.160 .154 .162 .184	6.72 6.67 6.91 6.87	.165	6.79
		. 0	202 A B C D	55 55 55 55	.089 .107 .089 .096	6.44 6.34 6.39 6.27		-
	1500	15	45 A B	<b>3</b> 5 <b>3</b> 5	.534 .361	6.45 6.61	.448	6.53
			C D	45 45	.337	6.80 6.43	.308	6.62
		TANKS TO THE PROPERTY OF THE P	46 A B C D E	55 55 55 55 55	.272 .249 .262 .259 .230	6.32 6.34 6.15 6.53 7.15	. 254	6.50
		10	61 A B	<b>3</b> 5 <b>3</b> 5	.353	6.26 6.54	.320	6.40
			CD	45 45	.235	6.32 6.41	.224	6.37
		The state of the s	62 A B C D 63 A B	55 55 55 55 55 55	.156 .161 .197 .192 .185	6.72 6.57 6.45 6.09 6.59 6.57	.173	6.50
THE TAXABLE PROPERTY OF TAXABLE PR	A THE STATE OF THE	5	66 A B	35 35	•143 •222	6.10 6.12	.183	6.11
	A CONTRACTOR OF THE CONTRACTOR		CD	45 45	.106 .101	5.98 5.97	.104	5.98

TABLE D-2. CONTINUED

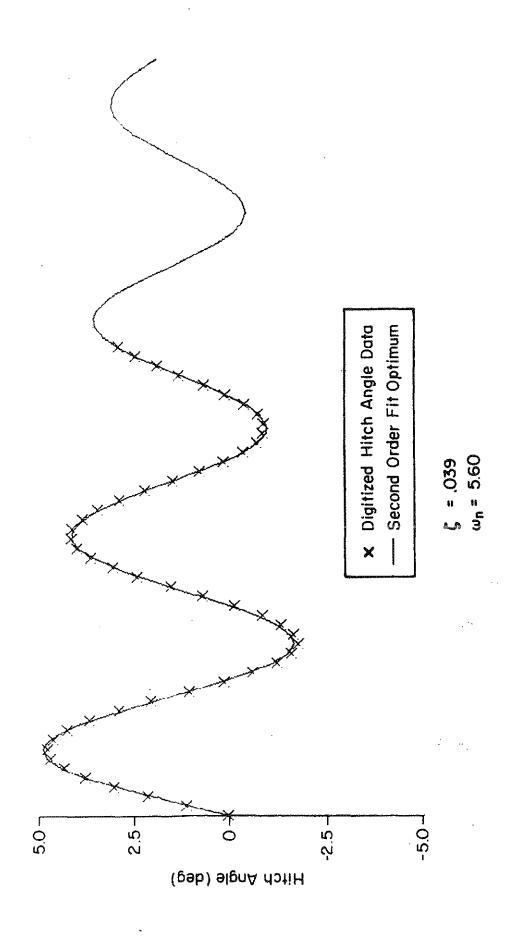
	TRAILER	HITCH LOAD	RUN	SPEED			AVEF	AGE	
TRAILER	WEIGHT	(%)	NUMBER	(MPH)	ζ	ωN	ζ	CiżN	
Utility (Cont)	1500	5	67 A B 68 A B	55 55 55 55	.044 .042 .063 .072	5.71 5.92 6.03 5.99	•055	5.91	
		0	69 A B	<b>3</b> 5 <b>3</b> 5	.176 .155	6.32 6.16	.166	6.24	
			C D	45 45	.092 .084	6.07 6.00	.088	6.04	
			71 A B C 72 A B	55 55 55 55 55	.042 .032 .036 .045 .039	5.79 6.01 5.61 5.40 5.60	.039	5,68	
	2600	10	83 A B C D	35 35 35 35 35	.213 .228 .232 .228	5.66 5.76 5.92 5.73	. 225	5.77	
				84 A B C . D	45 45 45 45	.153 .152 .154 .152	5.52 5.49 5.55 5.56	.153	5.53
			85 A B C D	55 55 55 55	.098 .105 .095 .104	5.51 5.56 5.47 5.32	.101	5.47	
		5 .	203 A 204 A	55 55	.056 .047	4.66 4.53	.052	4.60	
Camper	1600	15	105 A B C	35 35 35	.500 .368 .380	4.60 4.83 4.86	.416	4.76	
			D E	45 45	. 295 . 281	4.77 4.52	.288	4.65	
	·		106 A B C D E	55 55 55 55 55 55	.222 .248 .252 .254 .236	4.63 4.62 4.41 4.59 4.36	.242	4.52	

TABLE D-2. CONTINUED

-	TRAILER	HITCH	RUN	SPEED			AVE	AGE	
TRAILER	WEIGHT	LOAD (%)	NUMBER	(MPH)	ζ	ωn	ζ	Φ'n	
Camper (Cont)	1600	10	107 A B C D	55 55 55 55	.143 .158 .185 .157	4.80 4.84 5.06 4.76	.161	4.86	
,			108 A B	<b>3</b> 5 <b>3</b> 5	.336 .308	4.55 4.36	.322	4.46	
			C D	45 45	.237 .219	4.49 4.54	. 228	4.52	
		5		116 A B	<b>3</b> 5 <b>3</b> 5	•192 •204	4.94 4.89	.198	4.92
			C D	45 45	.165 .148	4.56 4.79	-157	4.68	
			117 A B C D 118 A B	55 55 55 55 55 55	.110 .100 .109 .100 .088 .091	4.60 4.71 4.58 4.66 4.67 4.73	.100	4.66	
		0	119 A B	<b>3</b> 5 <b>3</b> 5	.206 .261	4.91 4.70	.234	4.81	
			120 A 121 A 122 A 123 A	55 55 55 55	.074 .075 .080 .075	4.44 4.52 4.36 4.35	.076	4.42	
Travel	2400	15	160 A B	<b>3</b> 5 <b>3</b> 5	.357 .305	3.81 4.15	.331	3.98	
			CD	45 45	.250 .236	3.88 3.94	. 243	3.91	
			161 A B C 162 A B C	55 55 55 55 55 55	.194 .216 .150 .170 .216 .220	4.29 4.42 4.42 4.42 4.17 4.37	.194	4.35	

TABLE D-2. CONCLUDED

	TRAILER	HITCH	RUN	SPEED	SPEED ,	$\omega_{\mathbf{n}}$	AVERAGE			
TRAILER	WEIGHT	LOAD (%)		(MPH)	ζ		ζ	w <sub>n</sub>		
Travel (Cont)	2400	5	163 A B	35 35	.206 .256	4.34 4.14	.231	4.24		
				· C	45 45	.146 .144	4.19 4.00	<b>.1</b> 45	4.10	
	;	;	164 A B 165 A 166 A 167 A B	55 55 55 55 55 55 55 55	.058 .091 .063 .080 .066 .055	4.24 4.07 4.00 3.95 4.15 4.11 3.85	.067	4.05		
	10	189 A B	35 35	.259 .301	4.30 4.22	. 280	4.26			
					C D	45 45	.228 .196	4.09 4.21	.212	4.15
			190 A B 191 A B C	55 55 55 55 55	.142 .131 .118 .125 .124	4.20 4.00 4.25 4.06 4.09	.128	4.12		





TIME

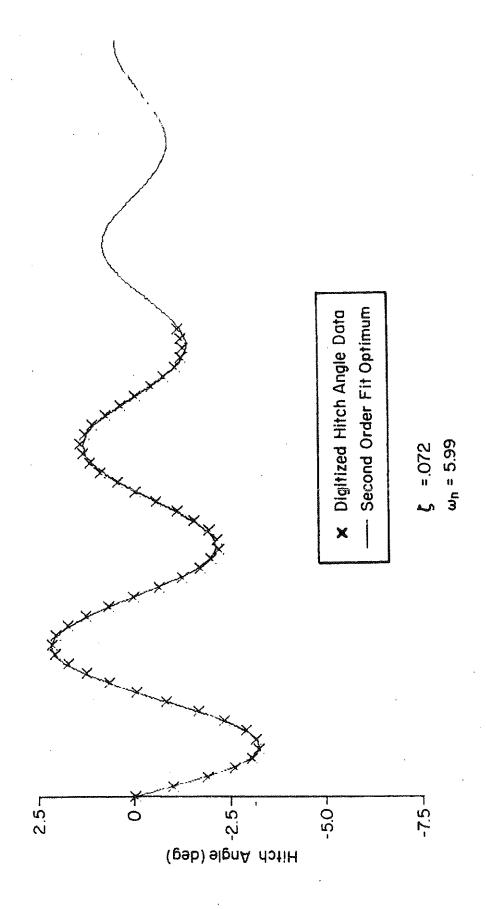


Figure D-2. Run 68, Horizon with 1500 lb U-Haul 5 Percent HL

TIME CEELS

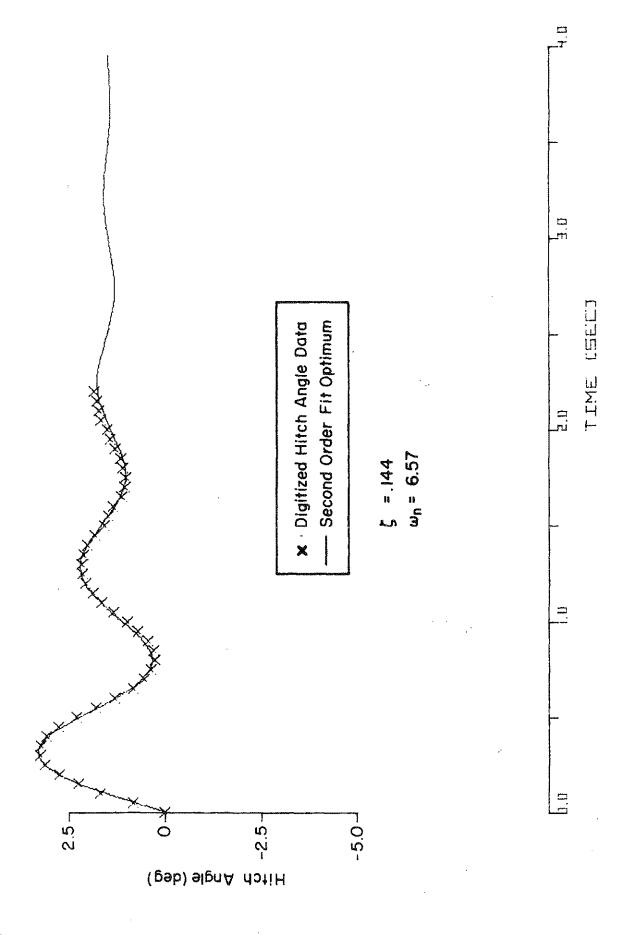


Figure D-3. Run 63, Horizon with 1500 lb U-Haul 10 Percent HL

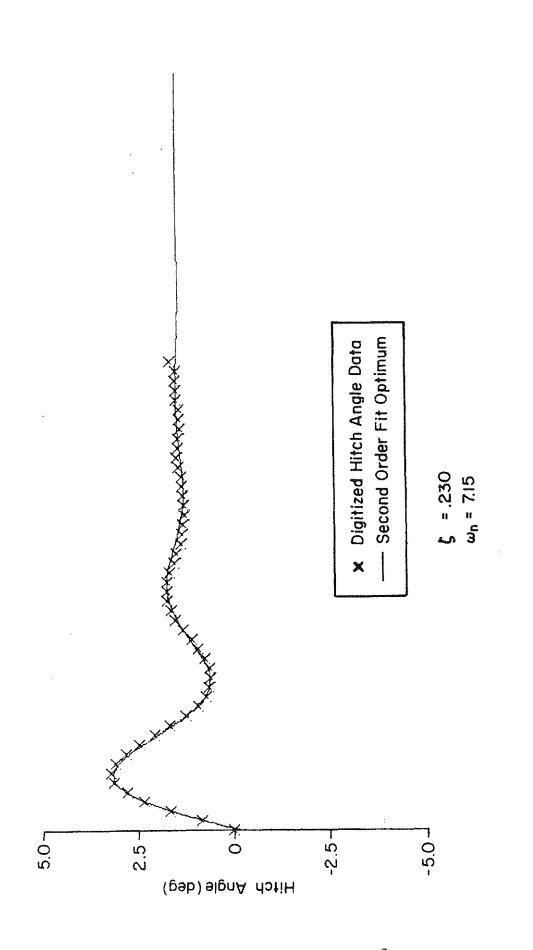


Figure D-4. Run 46, Horizon with 1500 lb U-Haul 15 Percent HL

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TIME

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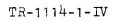
#### APPENDIX E

### TOW CAR STABILITY FACTOR DATA

This appendix presents constant radius circle (CRT) test results for all combination vehicles. In this test the speed and steering wheel angle are measured as the vehicle is maintained on a 200' radius circle. The driver attempted to maintain steady conditions at 15, 20, 25, 27-1/2, 30, 32-1/2, 35 and 37-1/2 mph. Lateral acceleration is then calculated from the average speed in any segment, i.e., ay =  $\frac{U^2}{R}$ . The average steering wheel angle was determined for the same speed segment. This is all a completely automated analysis procedure in which the FM data is digital and then averaged by digital computer.

The understeer gradient is then determined from the slope of the steering wheel angle divided by steering ratio vs. lateral acceleration. Since the slope changes above 0.3 g the slope from 0 to 0.3 g, as well as the overall slope (from 0 to 0.45 g) was measured.

In Figures E-1 through E-18 the line drawn through the data points represents a last square fit to the complete data set. The slope from 0 to 0.3 g is not drawn; only the slope is given.





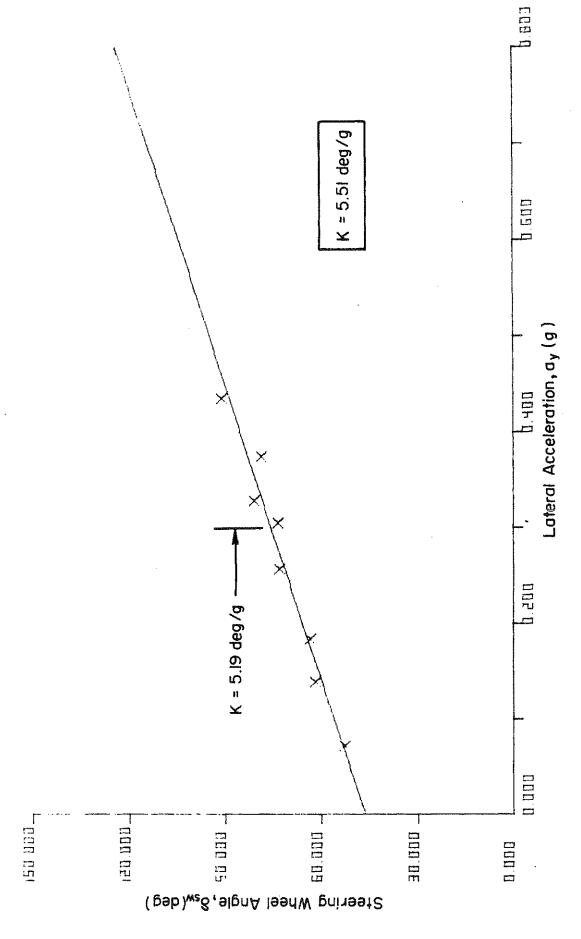


Figure E-1. Understeer Gradient for Citation Alone, Run 21

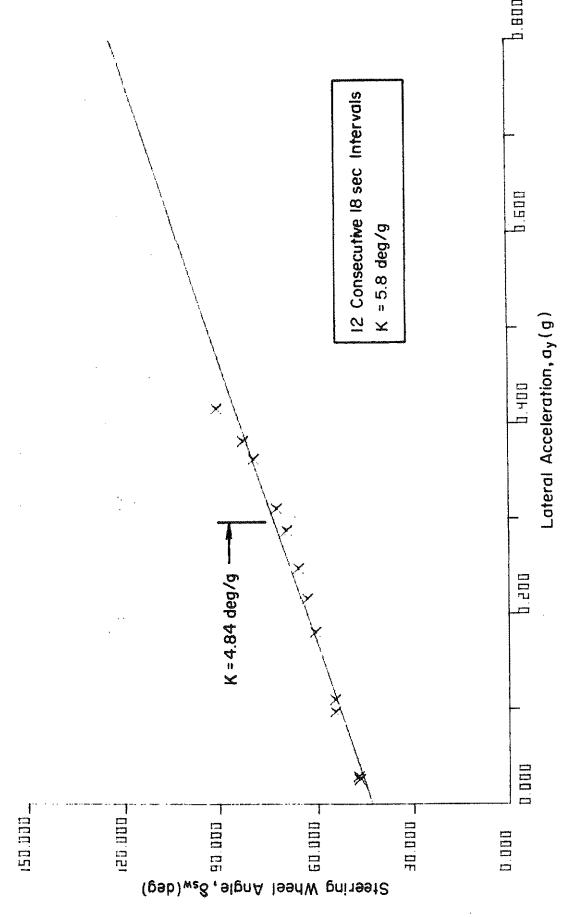


Figure E-2. Understeer Gradient for Citation Alone -- After Trailer Tests, Run 243

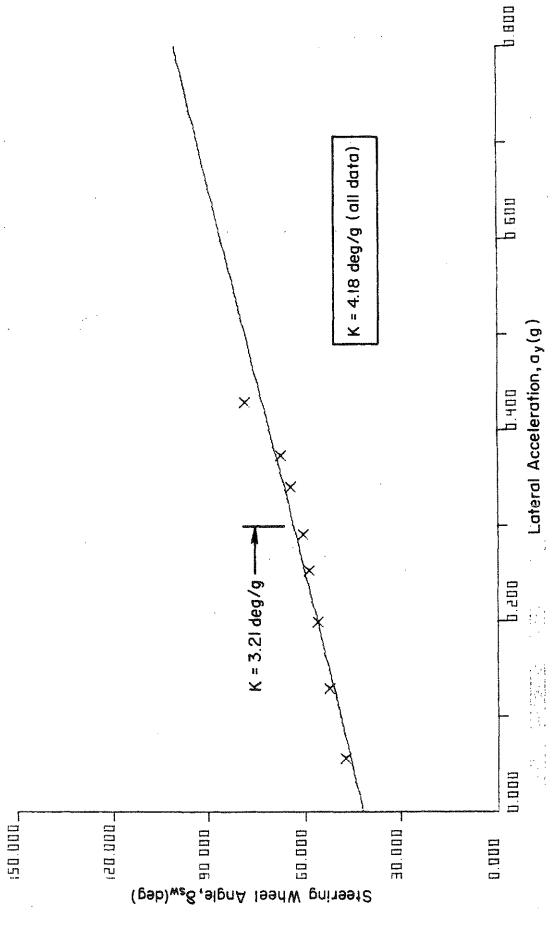
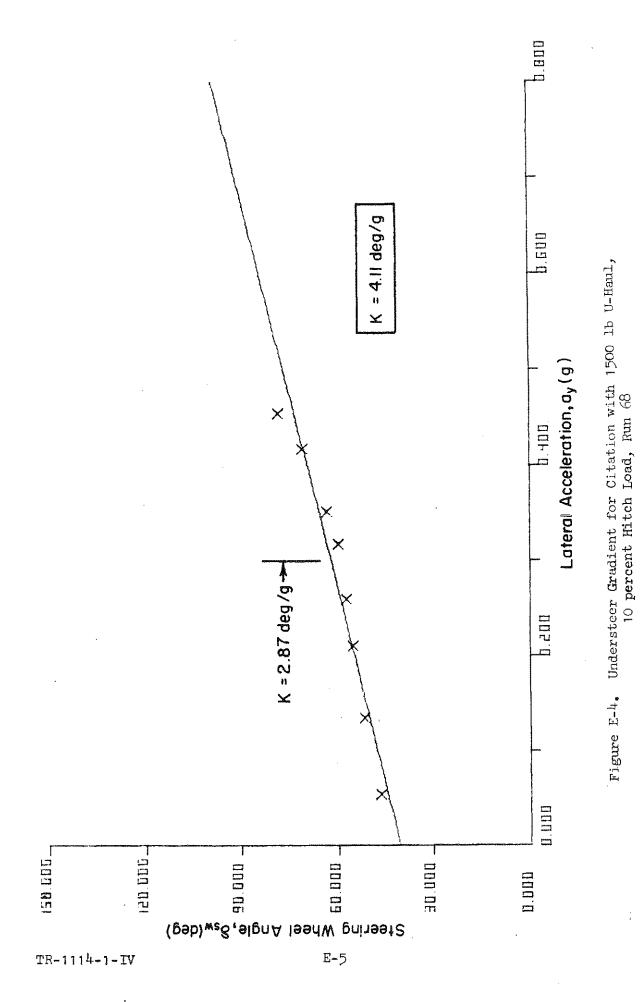


Figure E-3. Understeer Gradient for Citation with 1500 lb U-Haul, 5 percent Hitch Load, Run 69



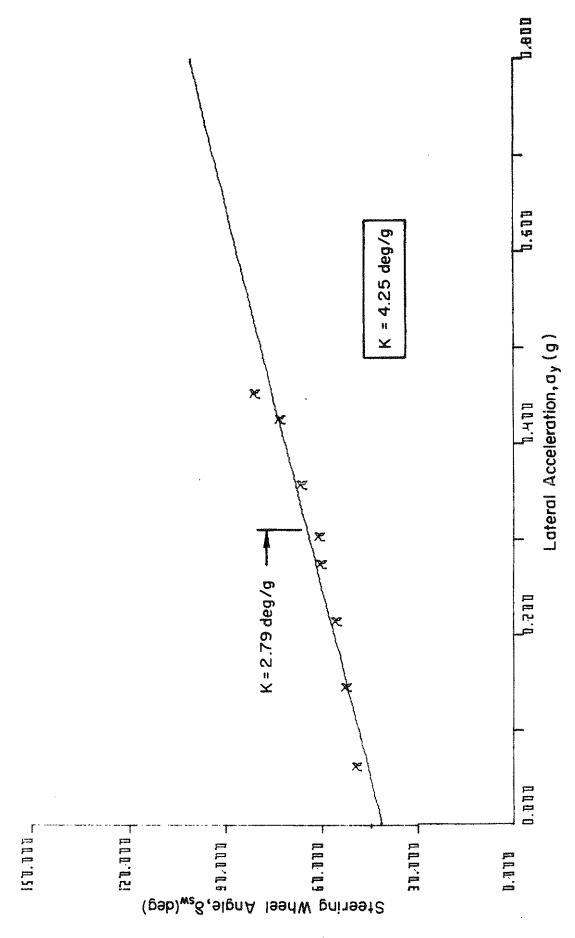


Figure E-5. Understeer Gradient for 1500 lb U-Haul, 15 percent Hitch Load, Run 41a

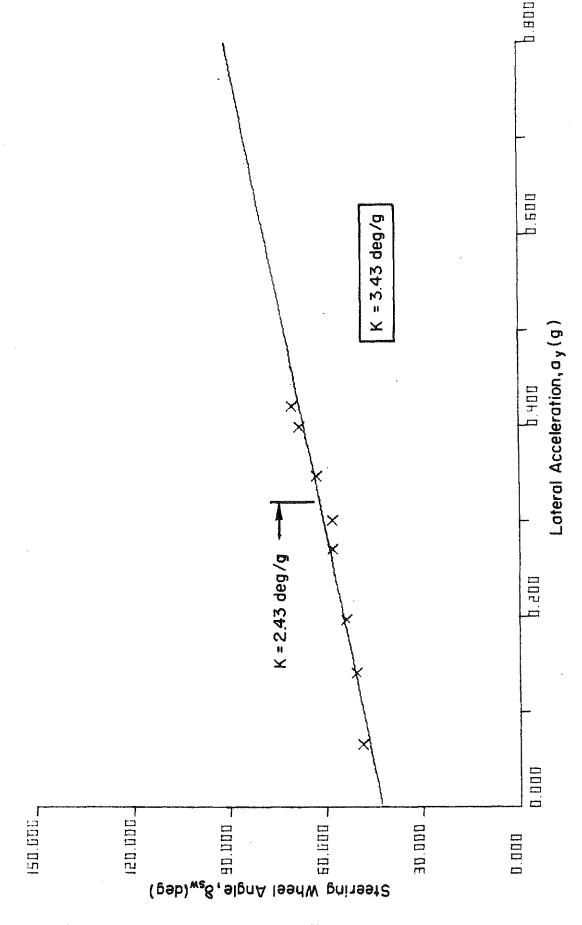


Figure E-6. Understeer Gradient for Citation with 1500 lb U-Haul, 20 percent Hitch Load, Run  $^{\rm hO}$ 

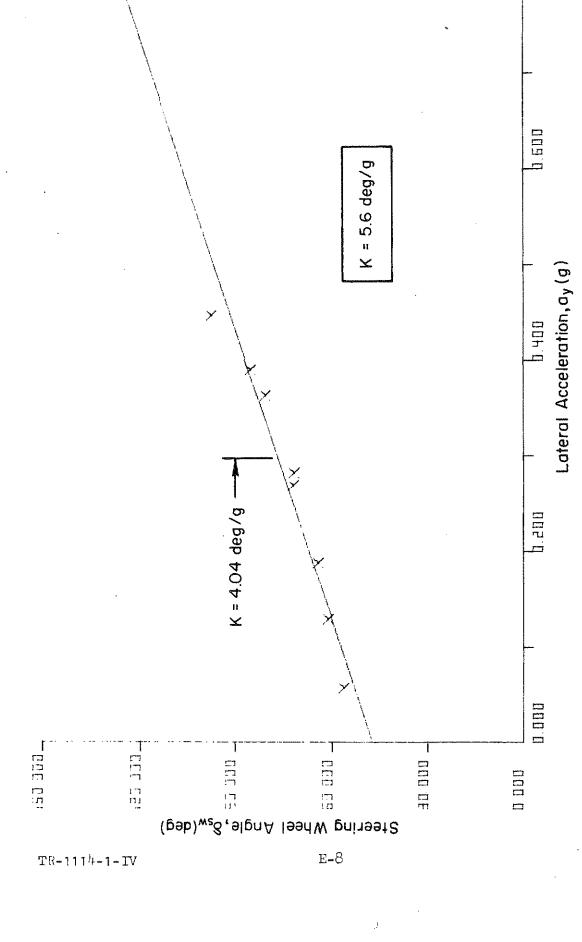


Figure E-7. Understeer Gradient for Citation with 1600 lb Camper, 10 Percent Hitch Load, Run 107

D. 8 DU

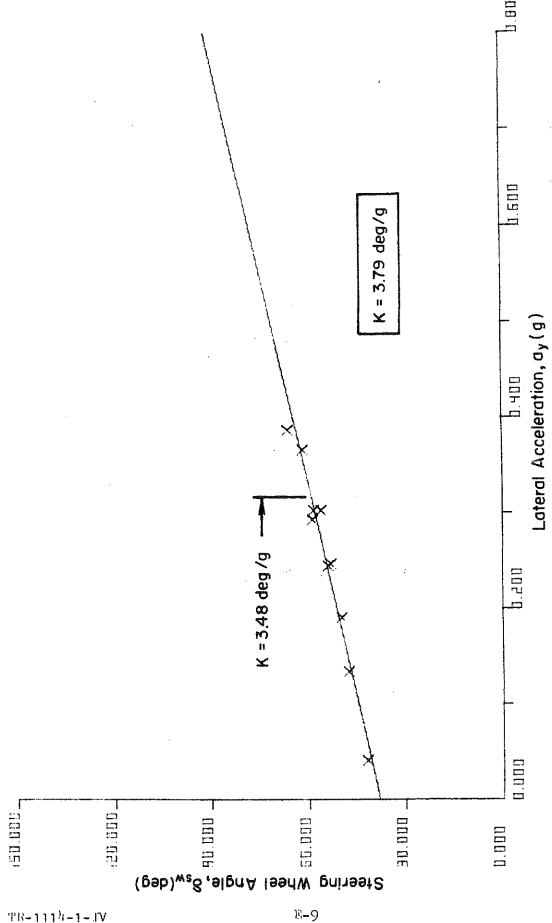


Figure E-8. Understeer Gradient for Citation with 2400 lb Travel, 10 percent Hitch Load; Runs 1876, 184, and 185

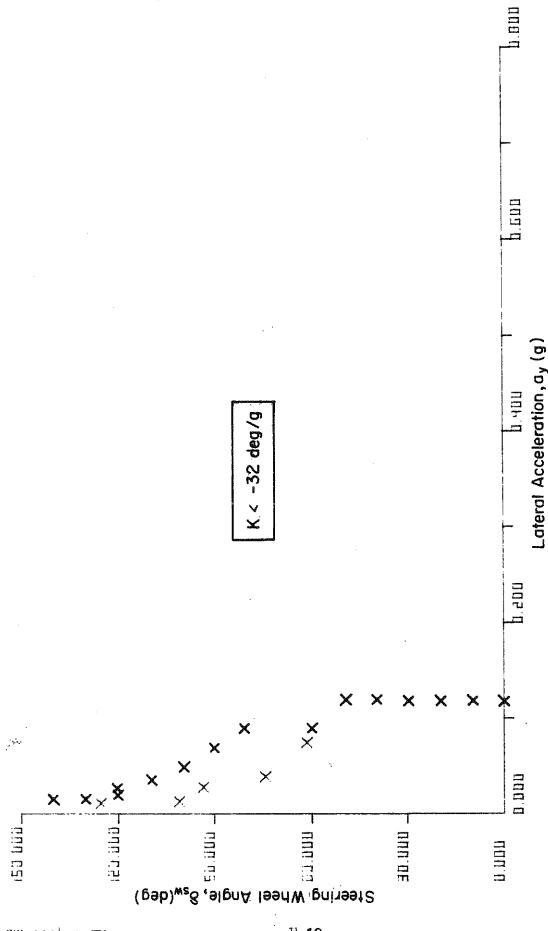
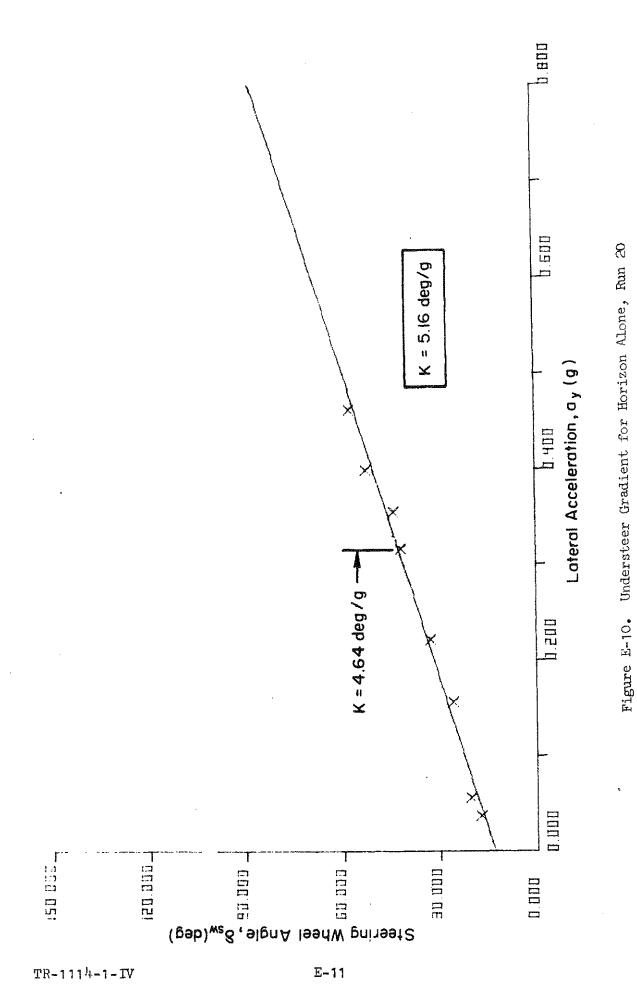


Figure E-9. Understeer Gradient for Citation with Travel Trailer, Rear Wheels Off Ground, Run 247

1. 27 M.



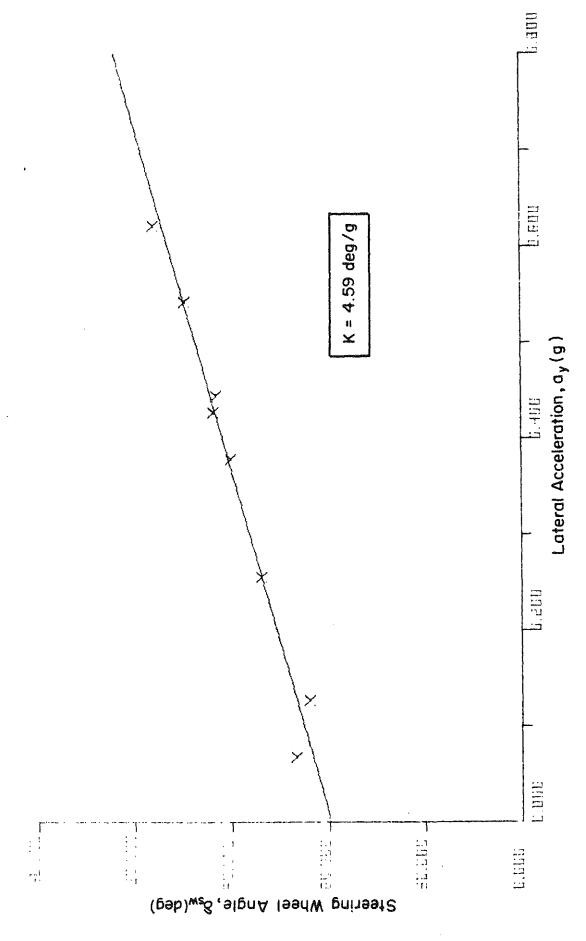


Figure E-11. Understeer Gradient for Horizon Alone -- After Utility and Camper Trailer Tests, Run 133

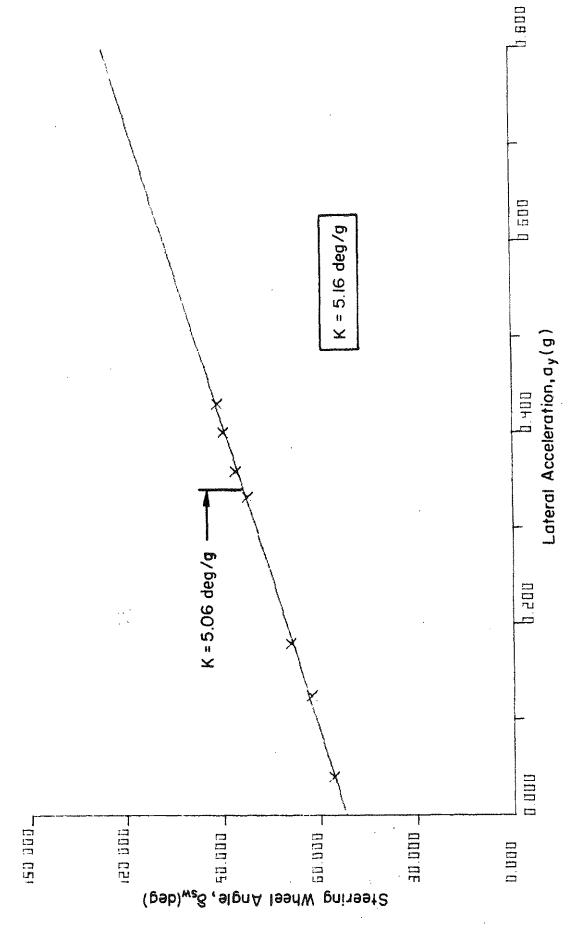
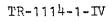


Figure E-12. Understeer Gradient for Horizon with 1500 lb U-Haul, 0 percent Hitch Load, Run 73





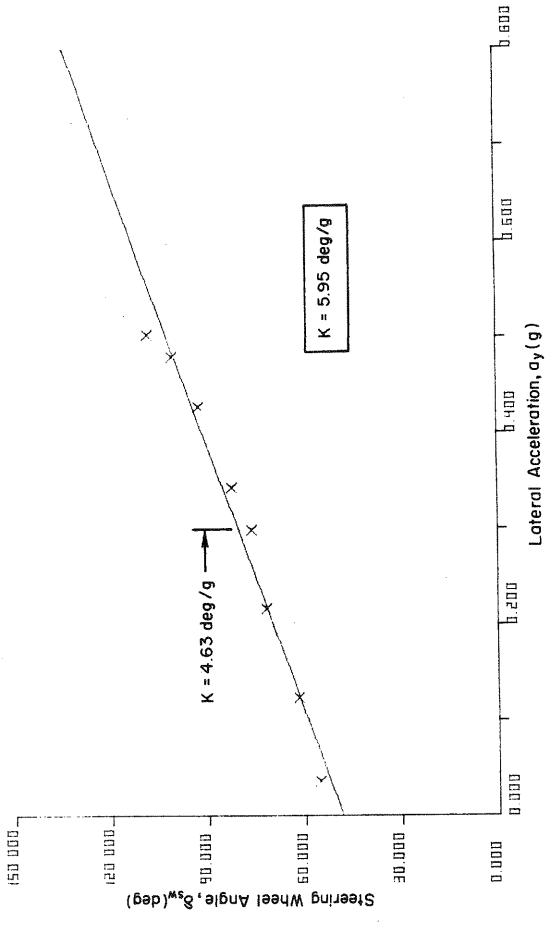
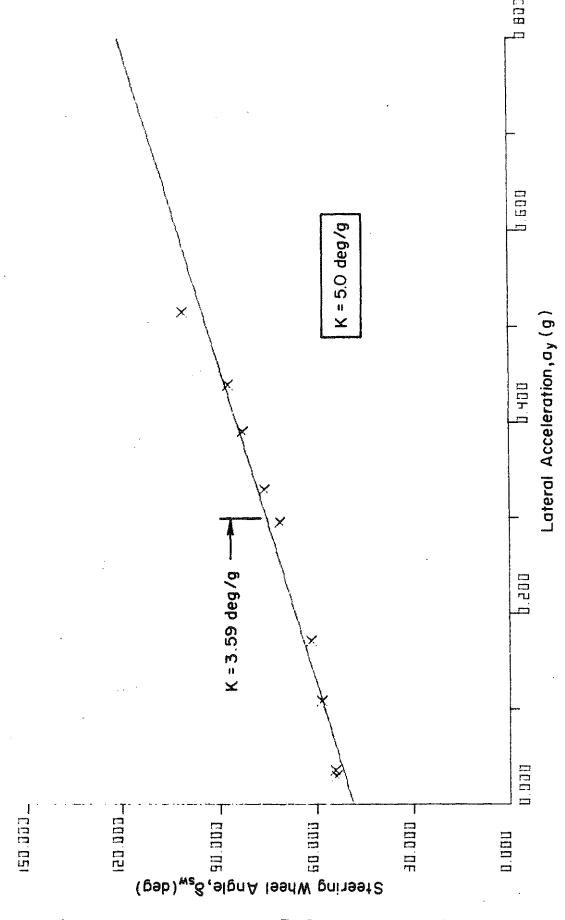


Figure E-13. Understeer Gradient for Horizon with 1500 lb U-Haul, 5 percent Hitch Load, Run 65



Understeer Gradient for Horizon with 1500 lb U-Haul, 10 percent Hitch Load, Run 61 Figure E-14.

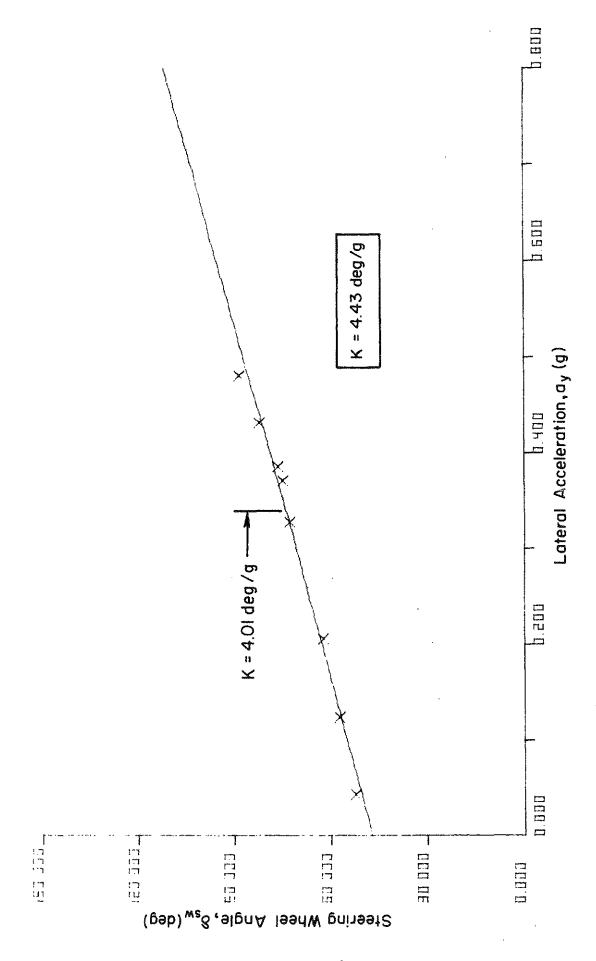


Figure E-15. Understeer Gradient for Horizon with 1500 lb U-Haul, 15 percent Hitch Load, Run 55

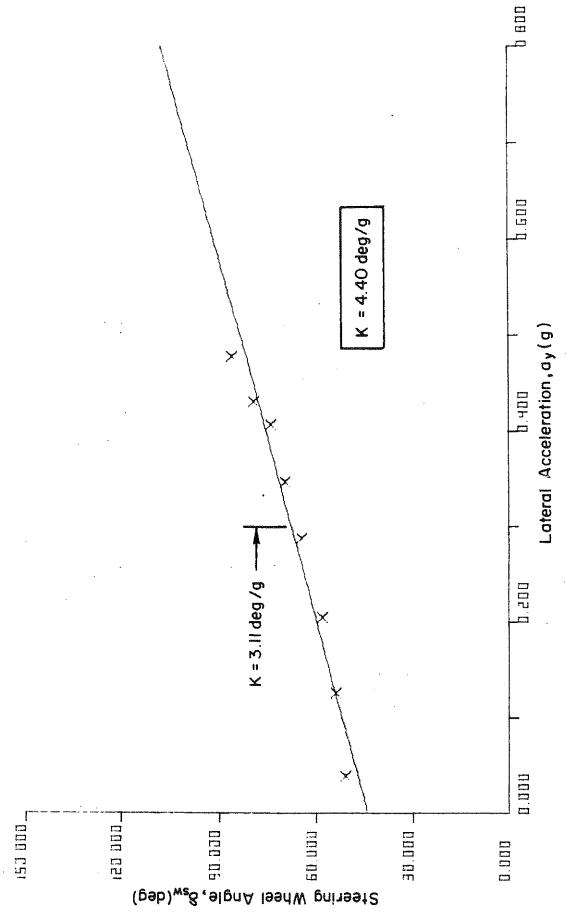
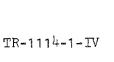


Figure E-16. Understeer Gradient for Horizon with 1500 lb U-Haul, 20 percent Hitch Load, Run 35

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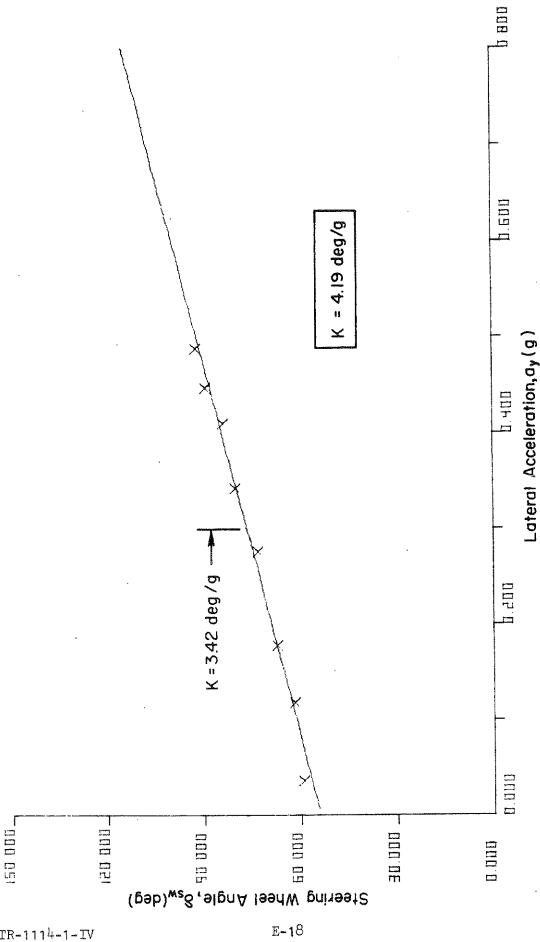


Figure E-17. Understeer Gradient for Horizon with 1600 lb Camper, 10 percent Hitch Load, Run 115

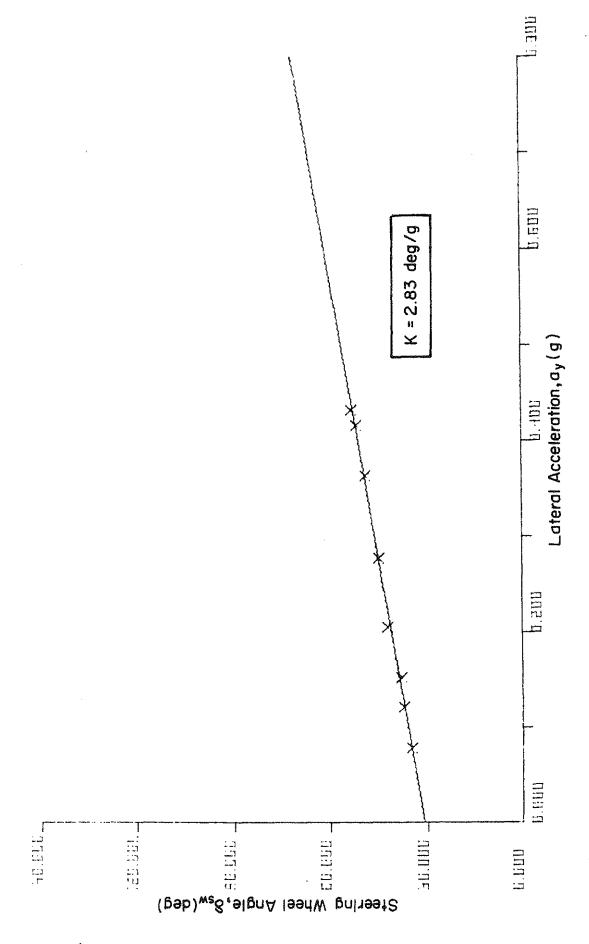


Figure E-18. Understeer Gradient for Horizon with 2400 lb Travel, 10 percent Hitch Load, Run 201

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